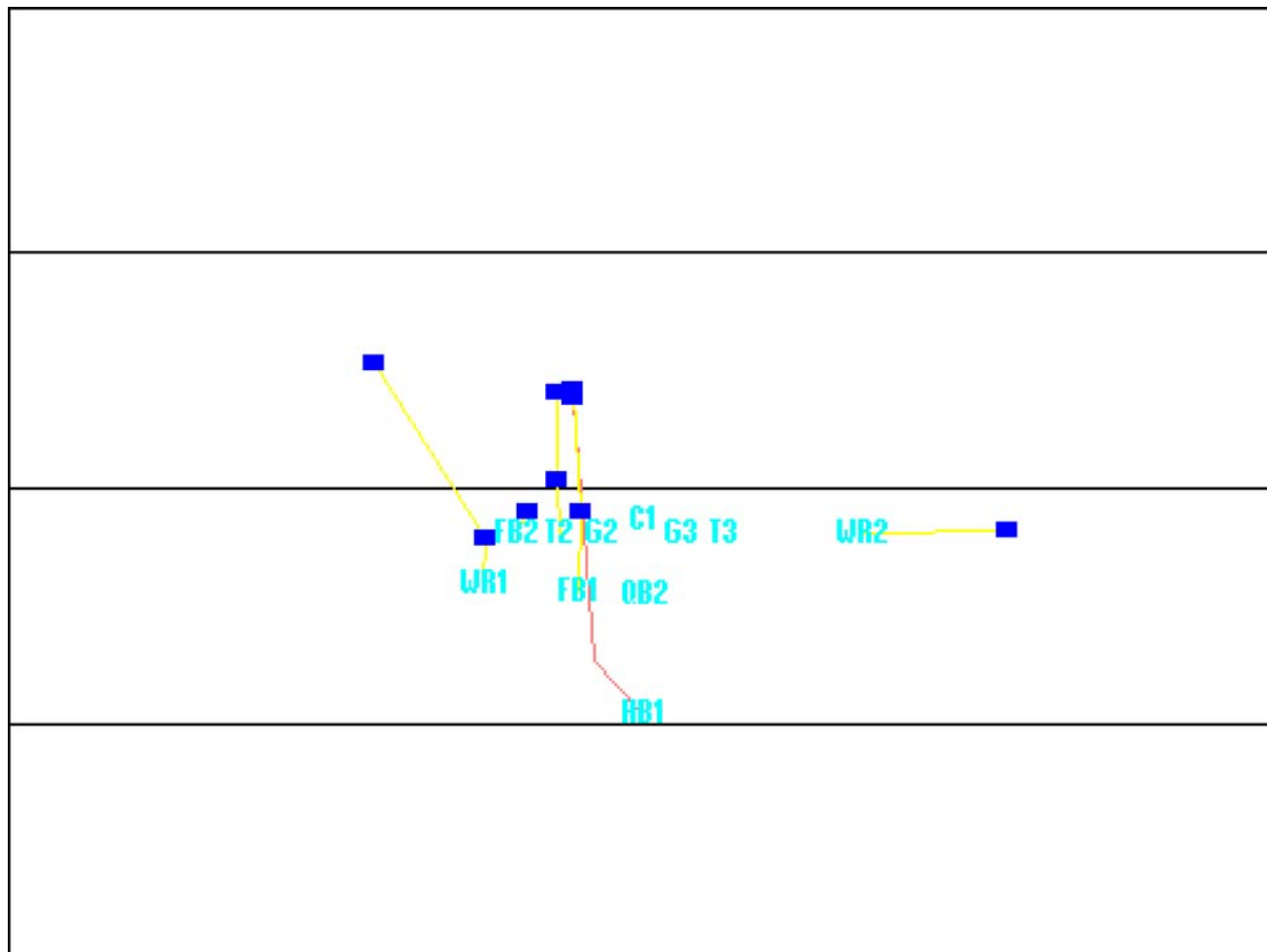
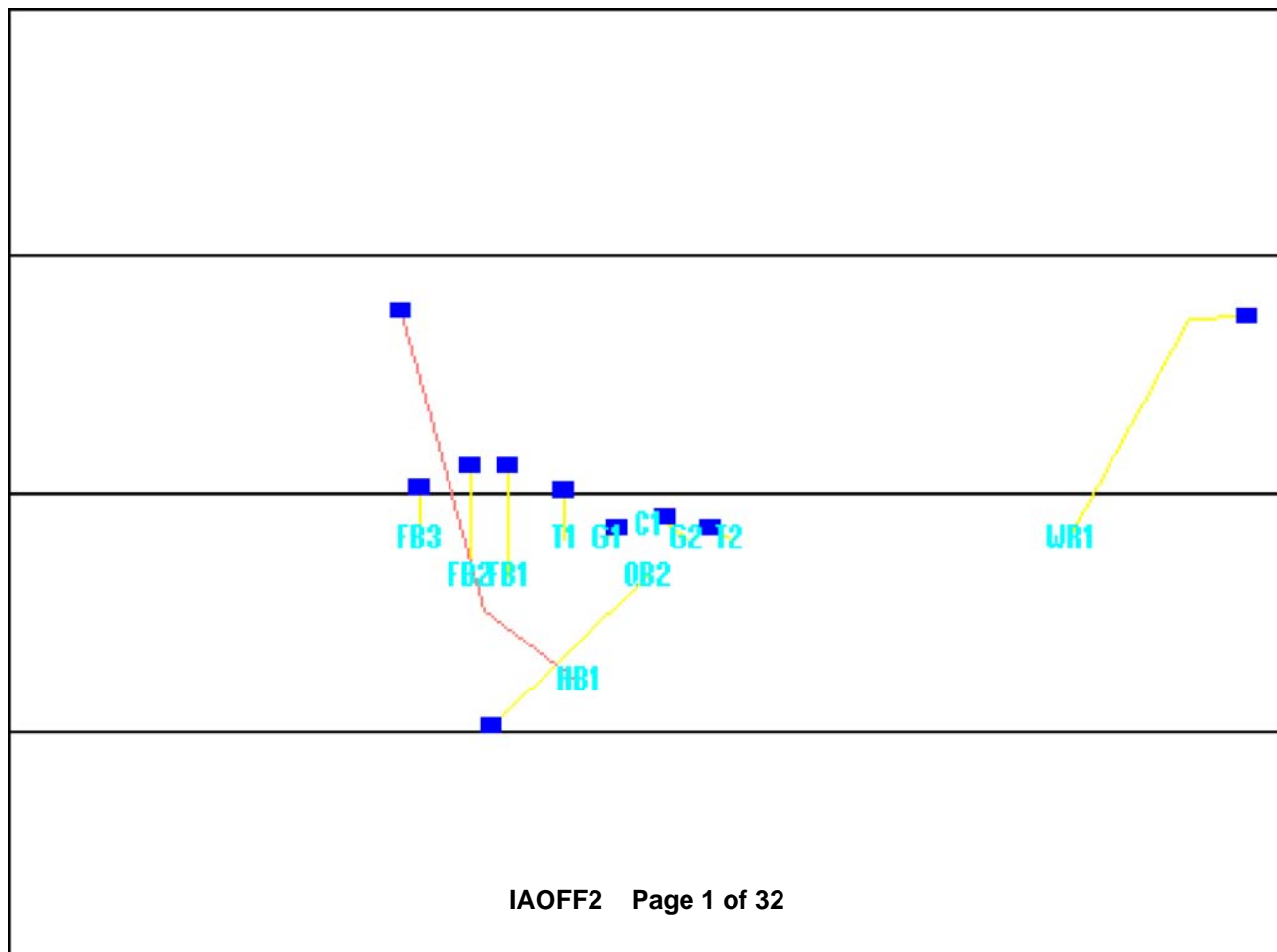


Game Plan:	IAOFF2
Team Name:	Iowa
Nickname:	Hawkeyes
Abbr:	IOWA
Coach:	Rob Boysen
League:	XFBS
Conference:	Blue
Division:	Fiesta Bowl

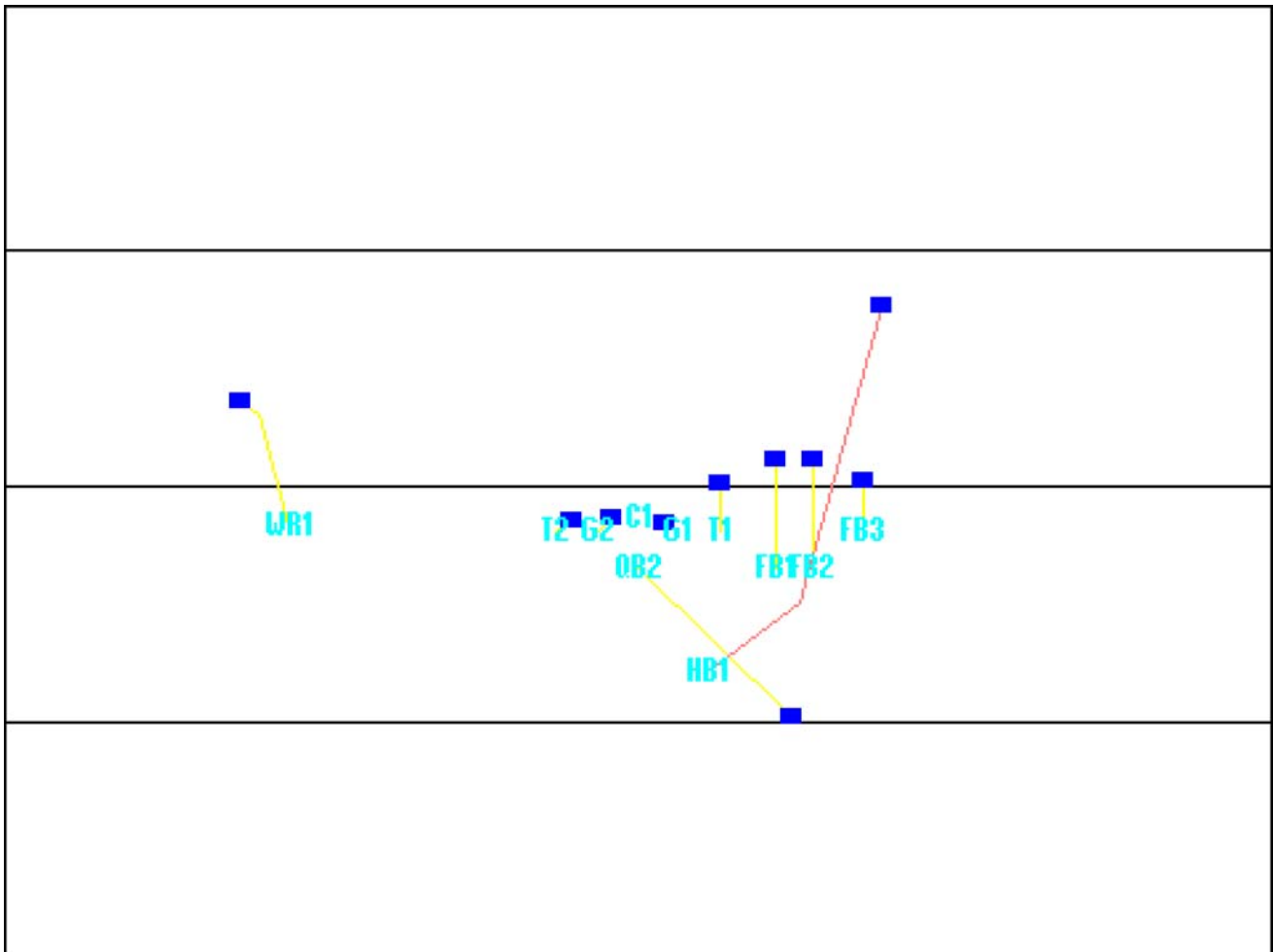
1-1 - GLR-1X - GOAL LINE RUN



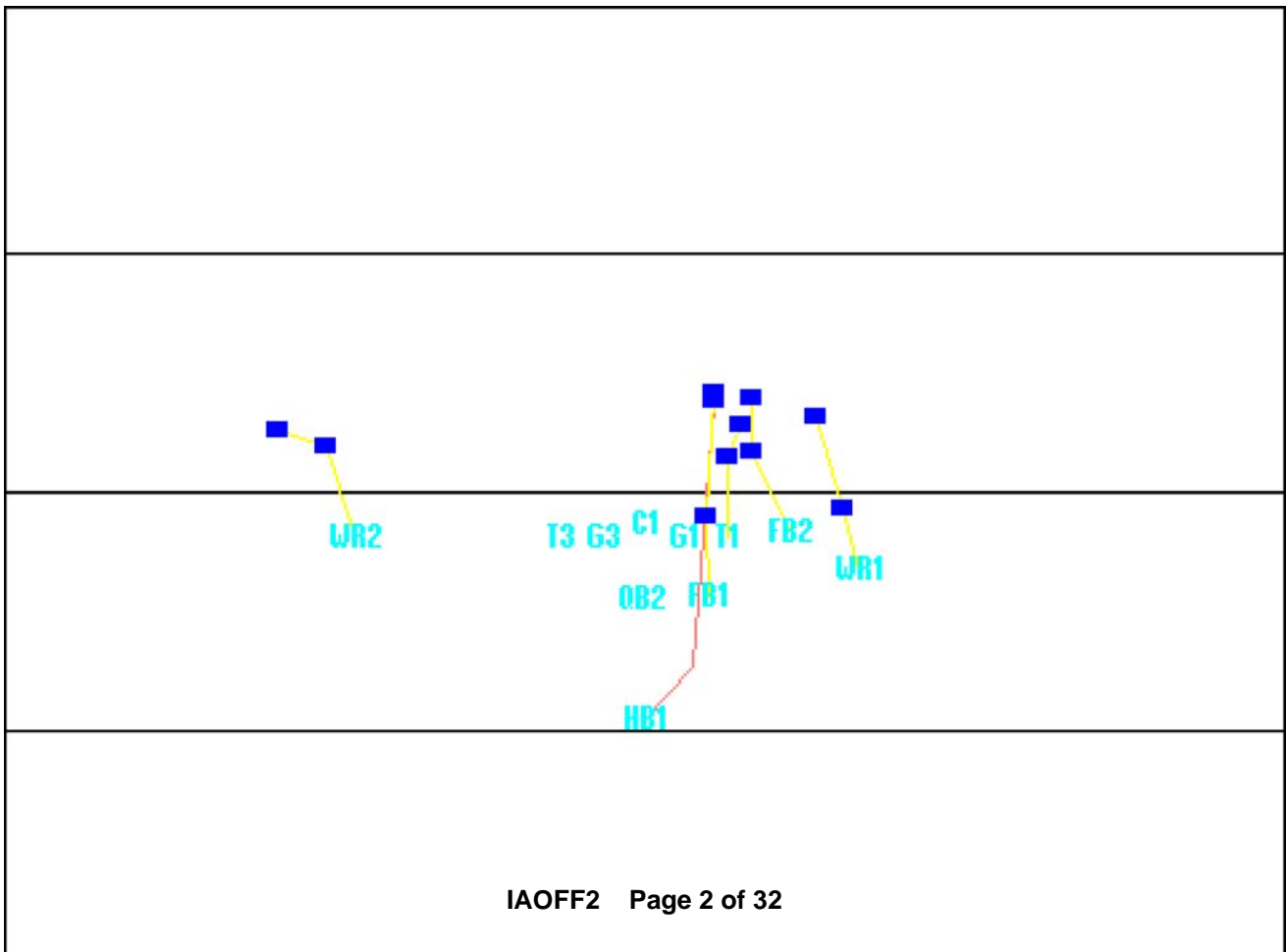
1-2 - GLRRL-RL - GOAL LINE RUN



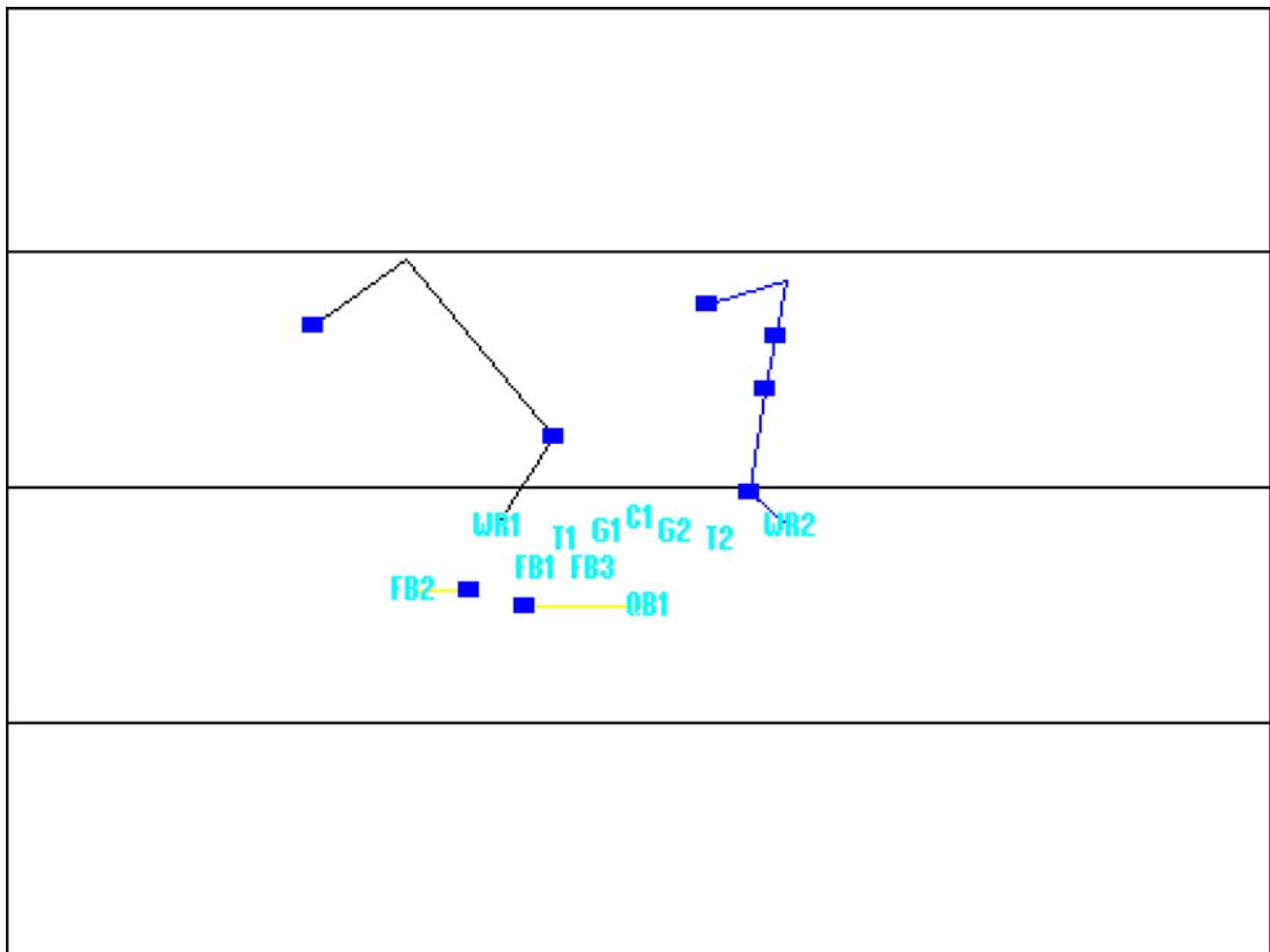
1-3 - GLRRX-RL - GOAL LINE RUN



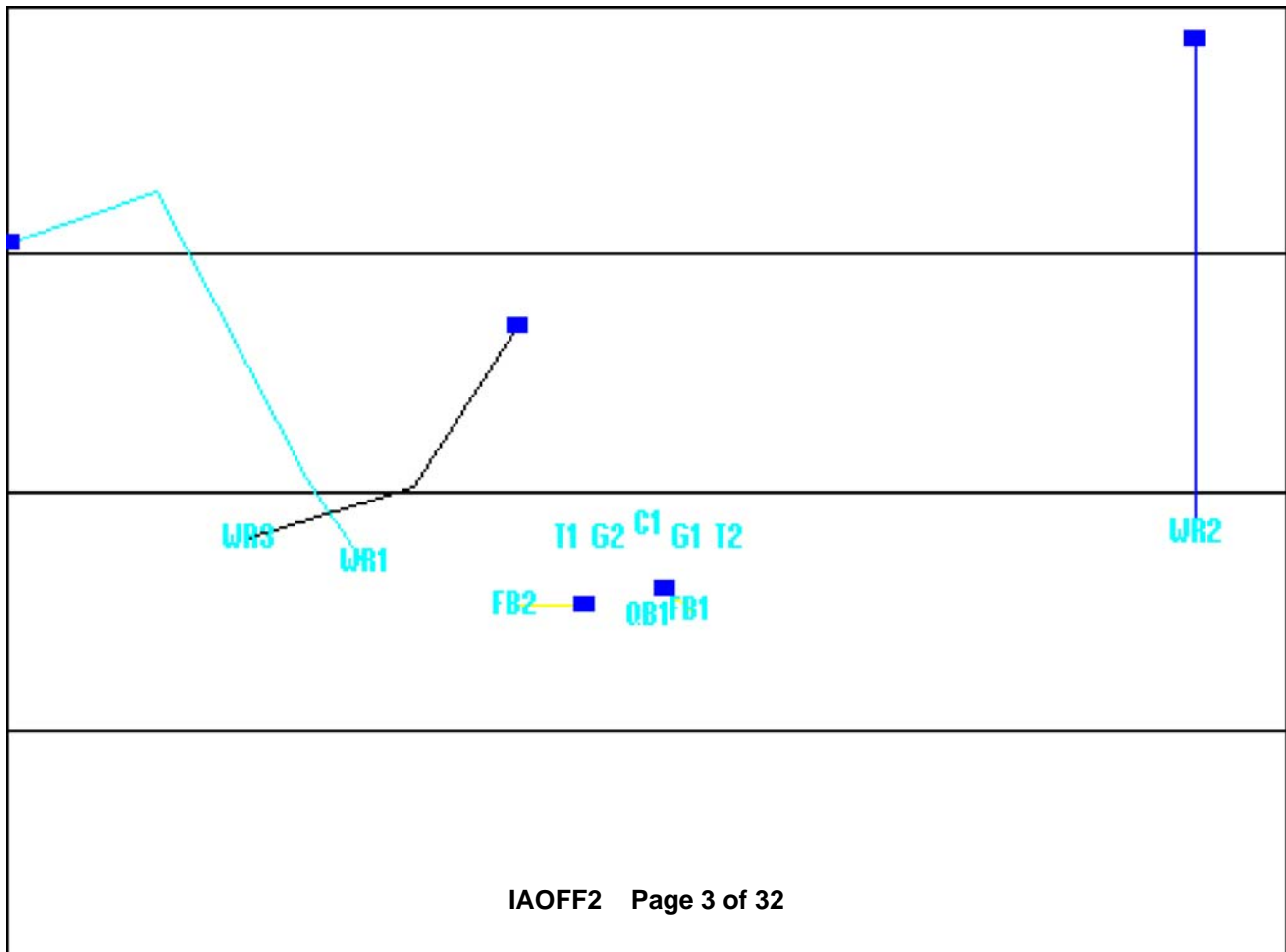
1-4 - GLR2X1 - GOAL LINE RUN



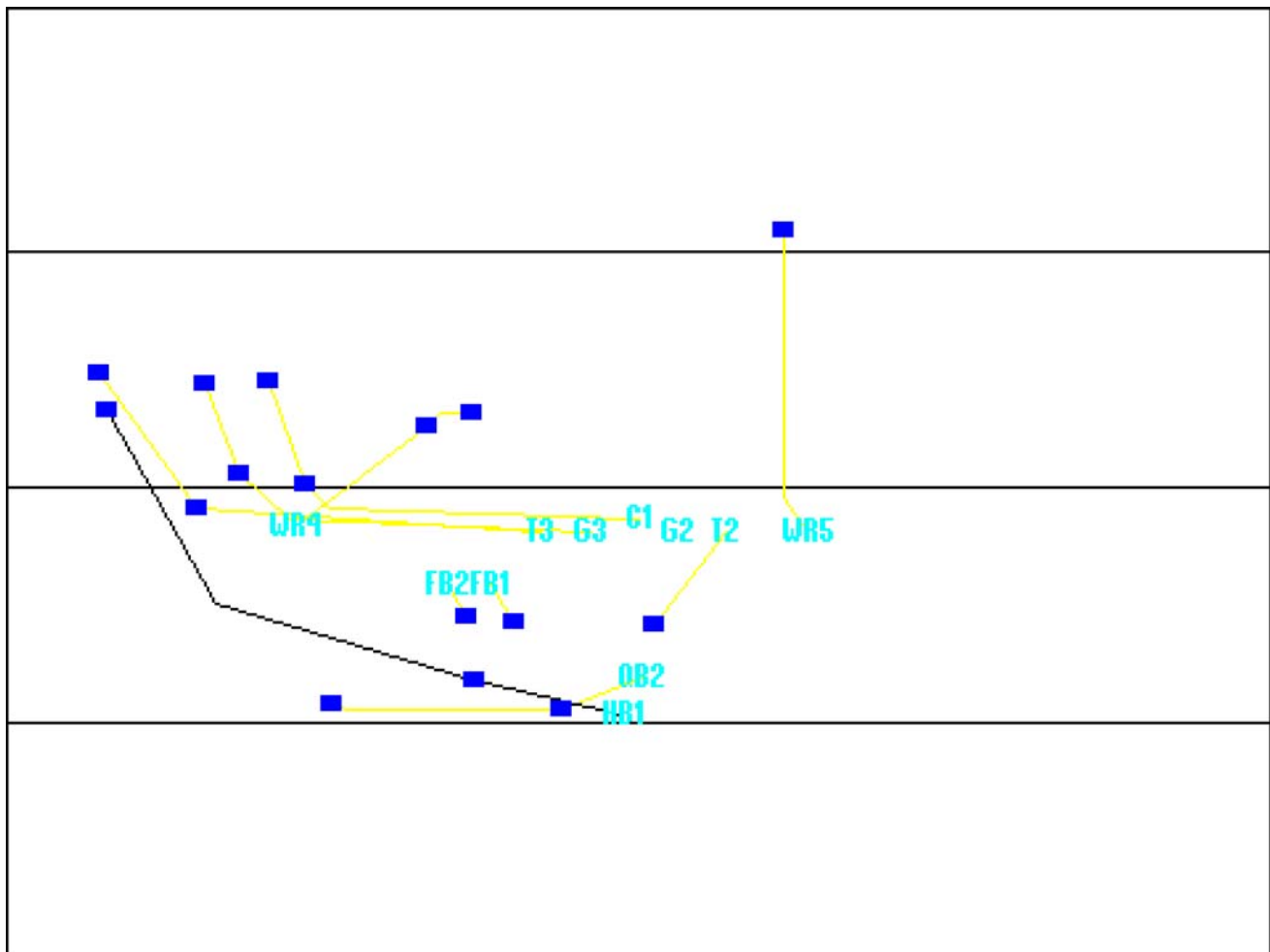
2-1 - RLsbk1x - RUN LEFT



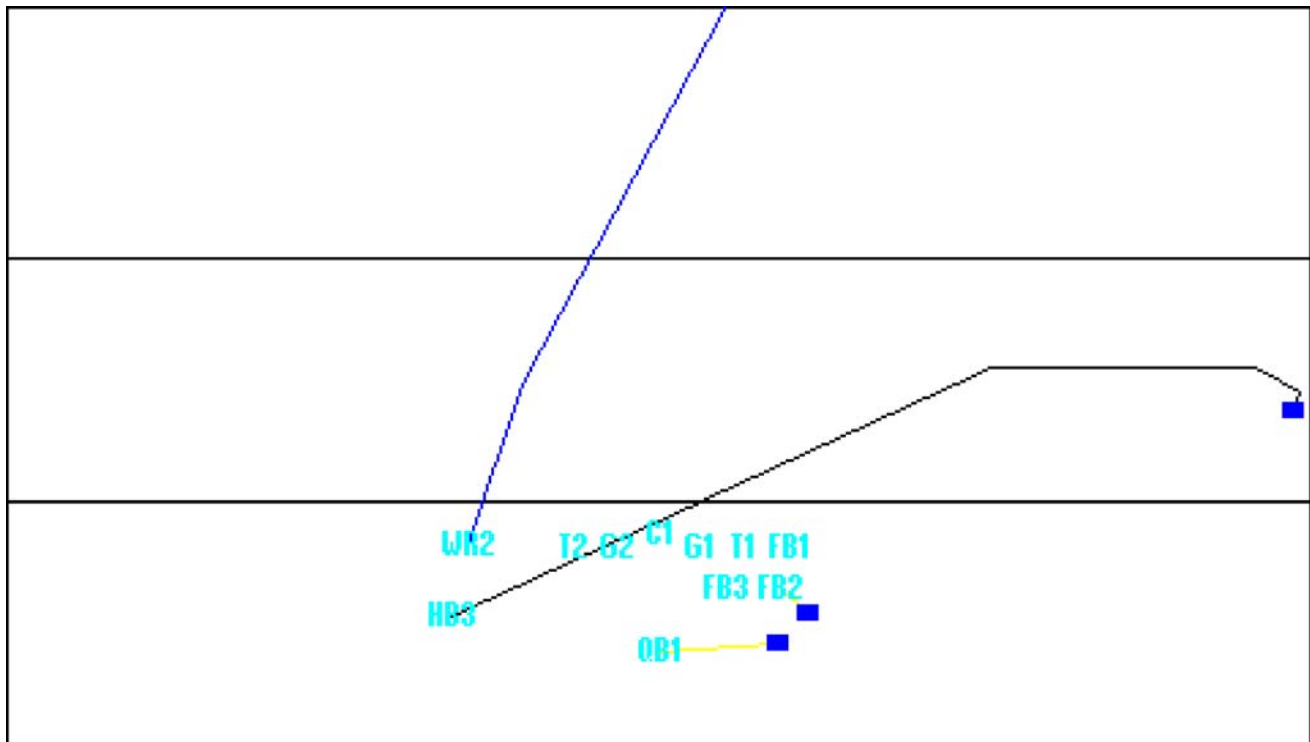
2-2 - RL911 - RUN LEFT



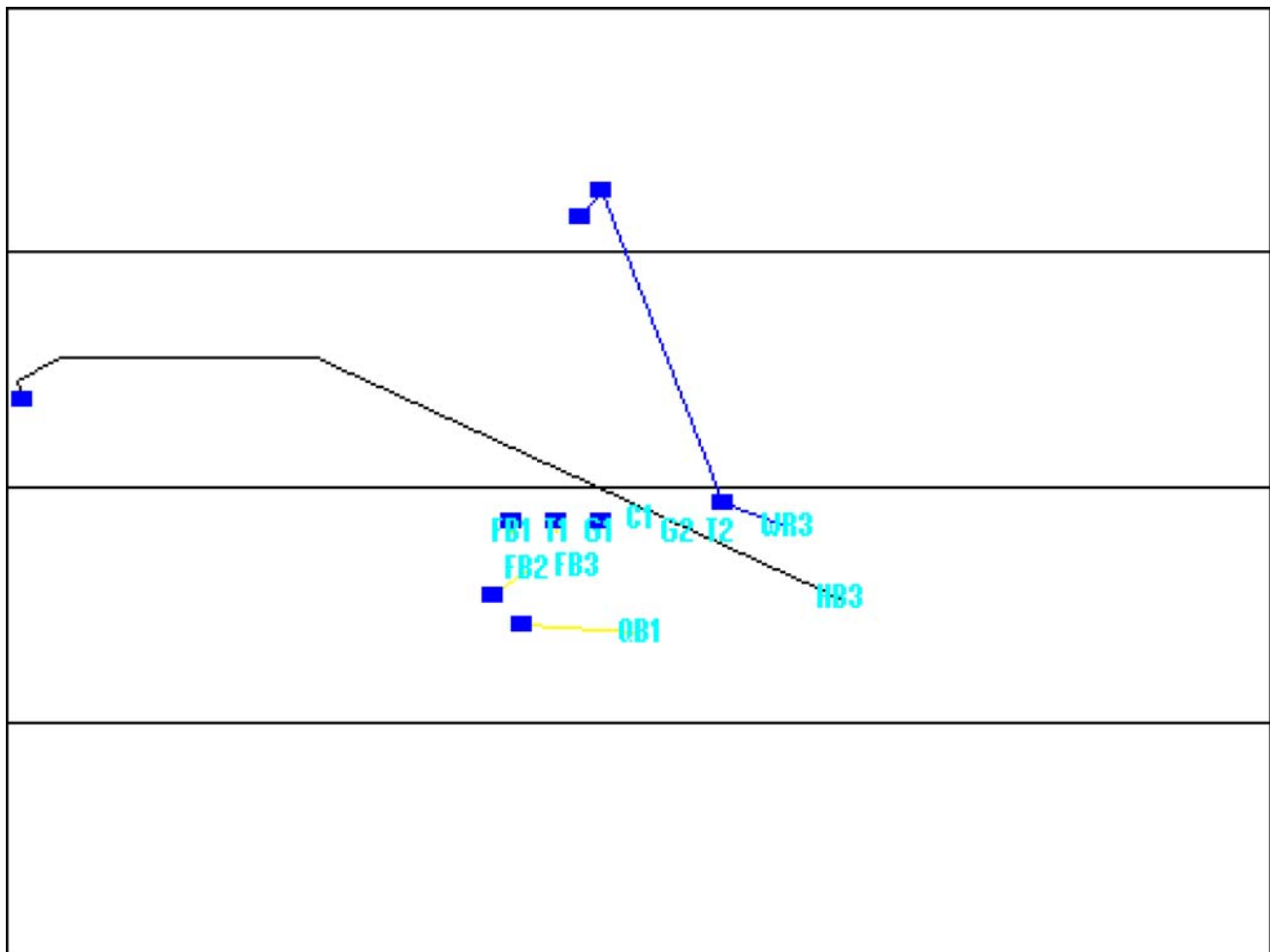
2-3 - RLBULL1 - RUN LEFT



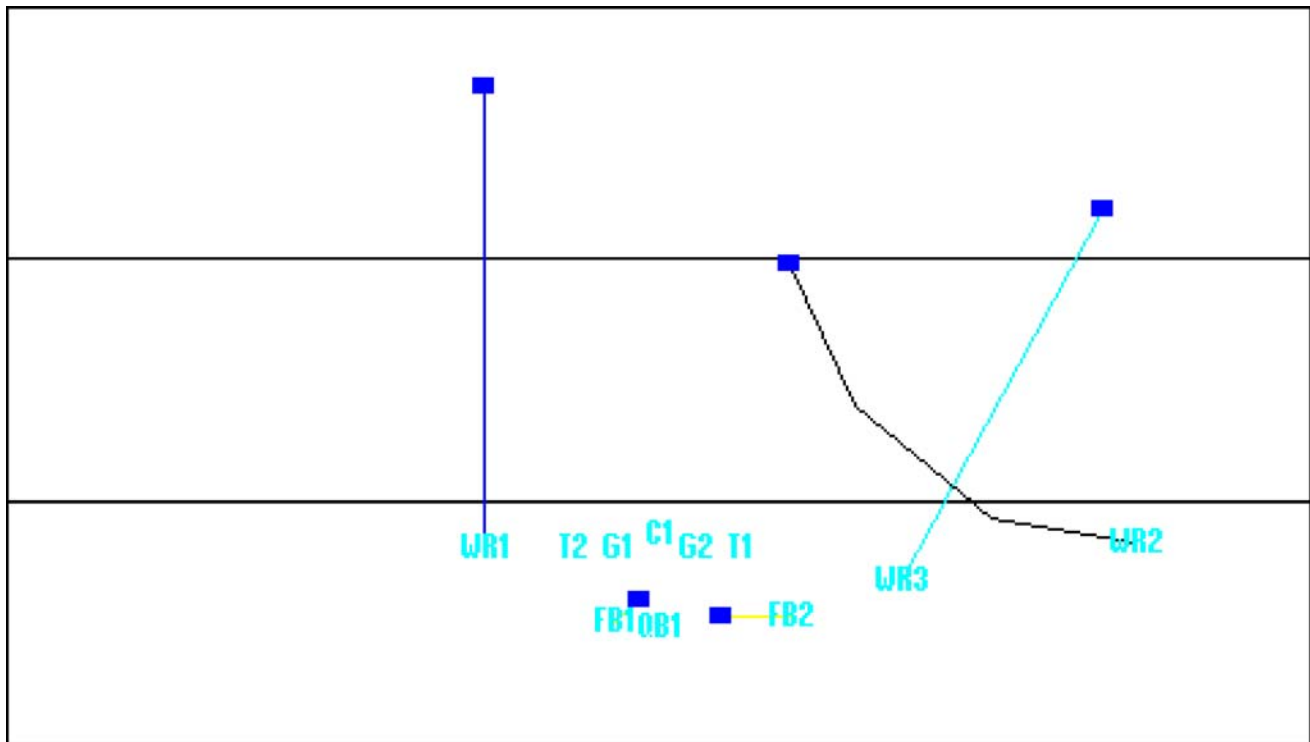
2-4 - RLHB3Z - RUN LEFT



3-1 - RRHB-R2 - RUN RIGHT



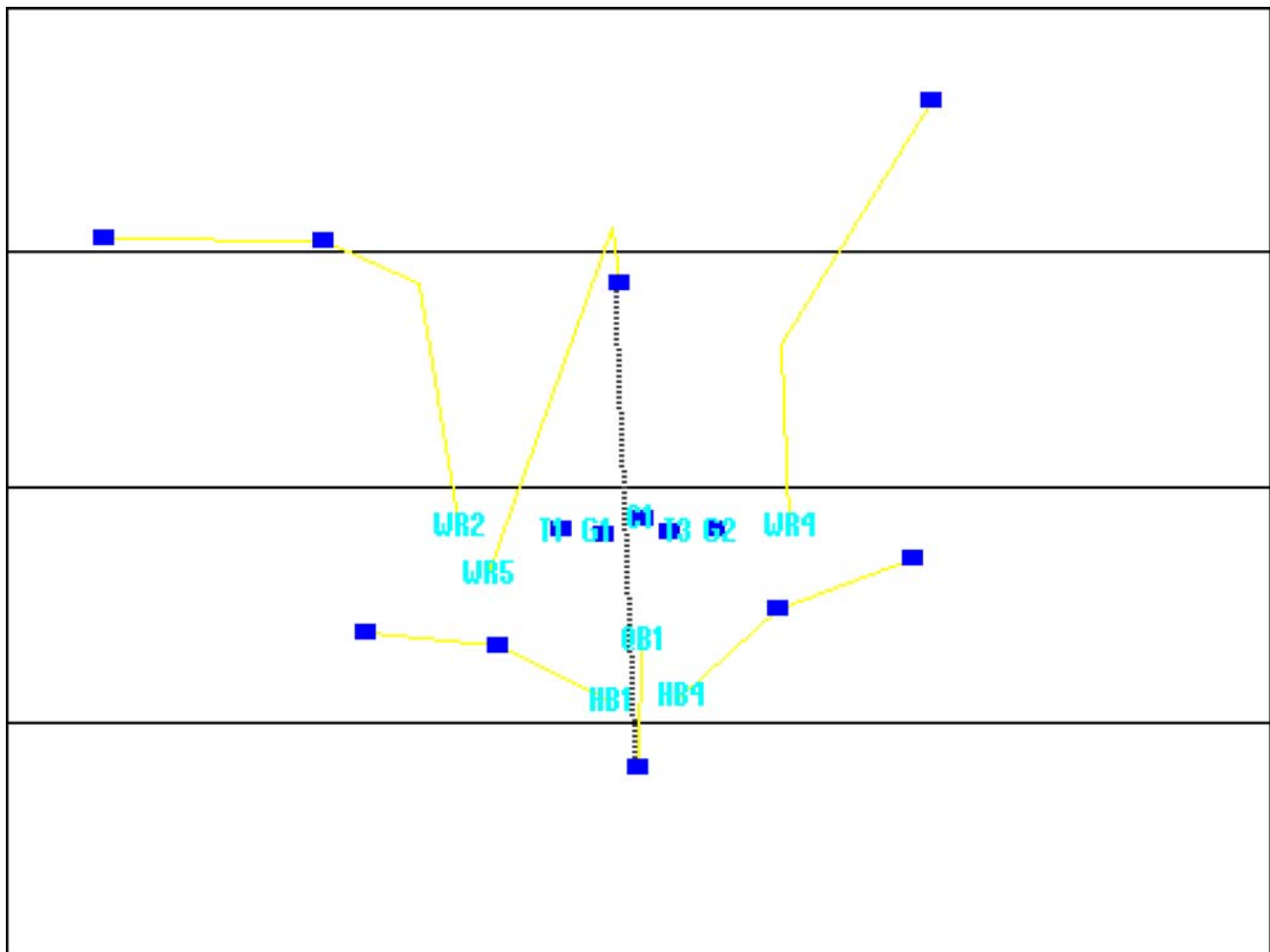
3-2 - RRG11a - RUN RIGHT



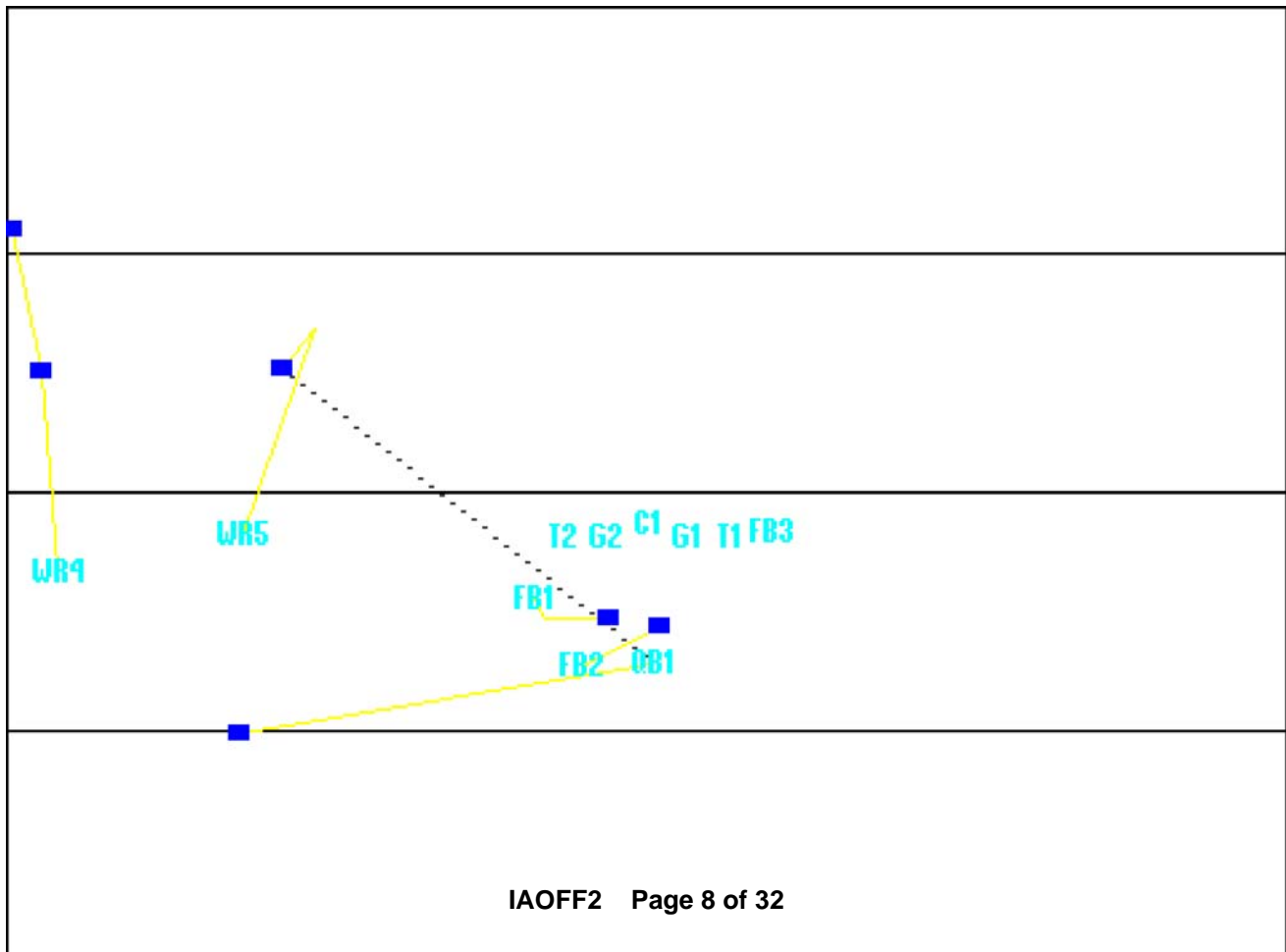
A diagram of a two-link robotic arm. The base is labeled 'OB1'. The first joint is labeled 'T1'. The first link is labeled 'G1'. The second joint is labeled 'T2'. The second link is labeled 'G2'. The end effector is labeled 'WR2'. The diagram also shows a reference path for the end effector, labeled 'WR1', and a feedback path labeled 'FB1' and 'FB3'. A yellow line connects 'OB1' to a point labeled 'FB2'.

The graph displays a series of data points connected by lines. The x-axis is labeled with 'FB3 T1 G1 C1 G2 T2' and the y-axis with 'QB1 FB2 FB1 WR5 WR4'. The data points are connected by lines, showing a general upward trend with some fluctuations. A dashed line connects the points for 'FB1' and 'WR5'.

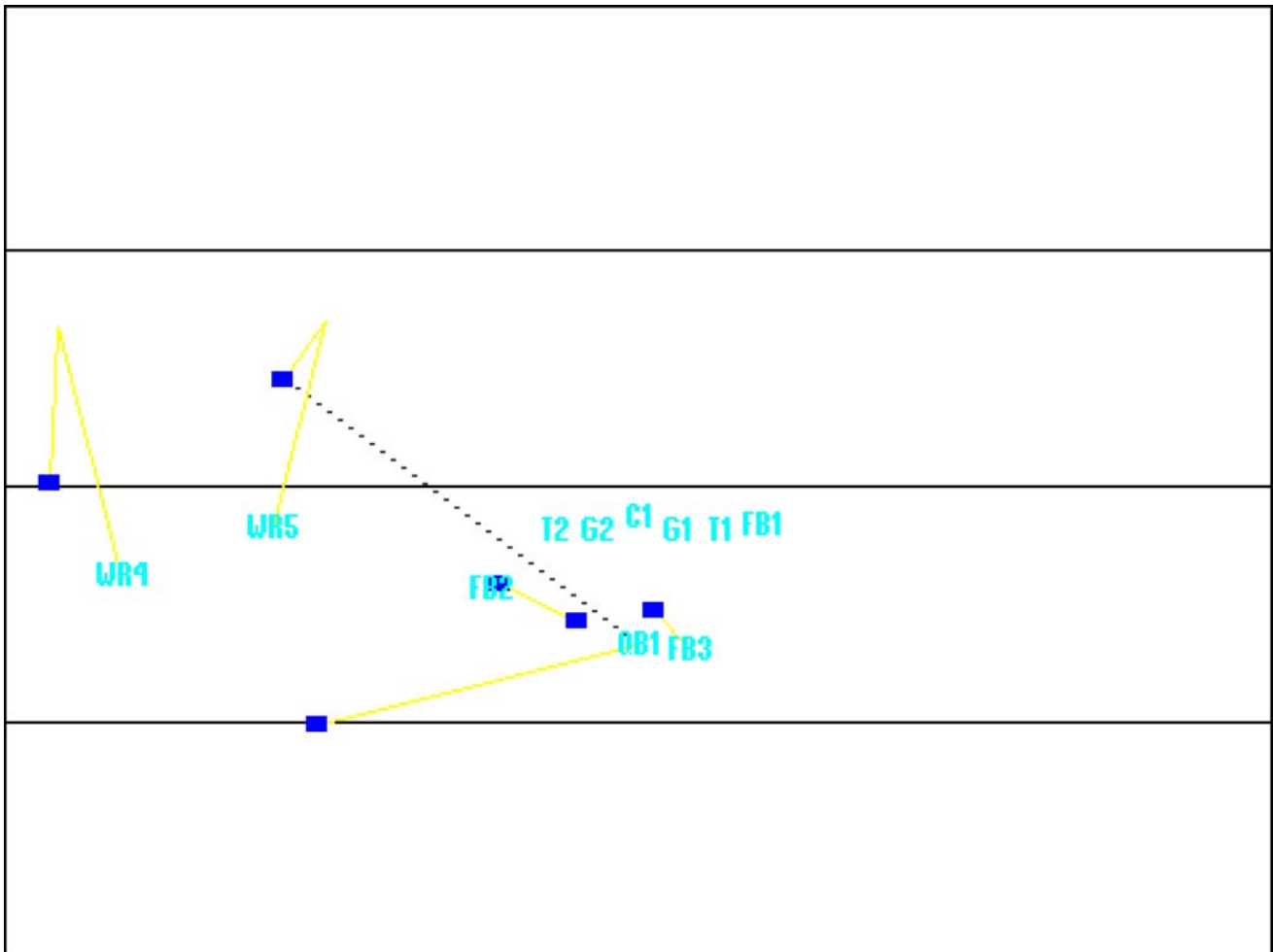
4-3 - RMRLLP1 - RUN MID.



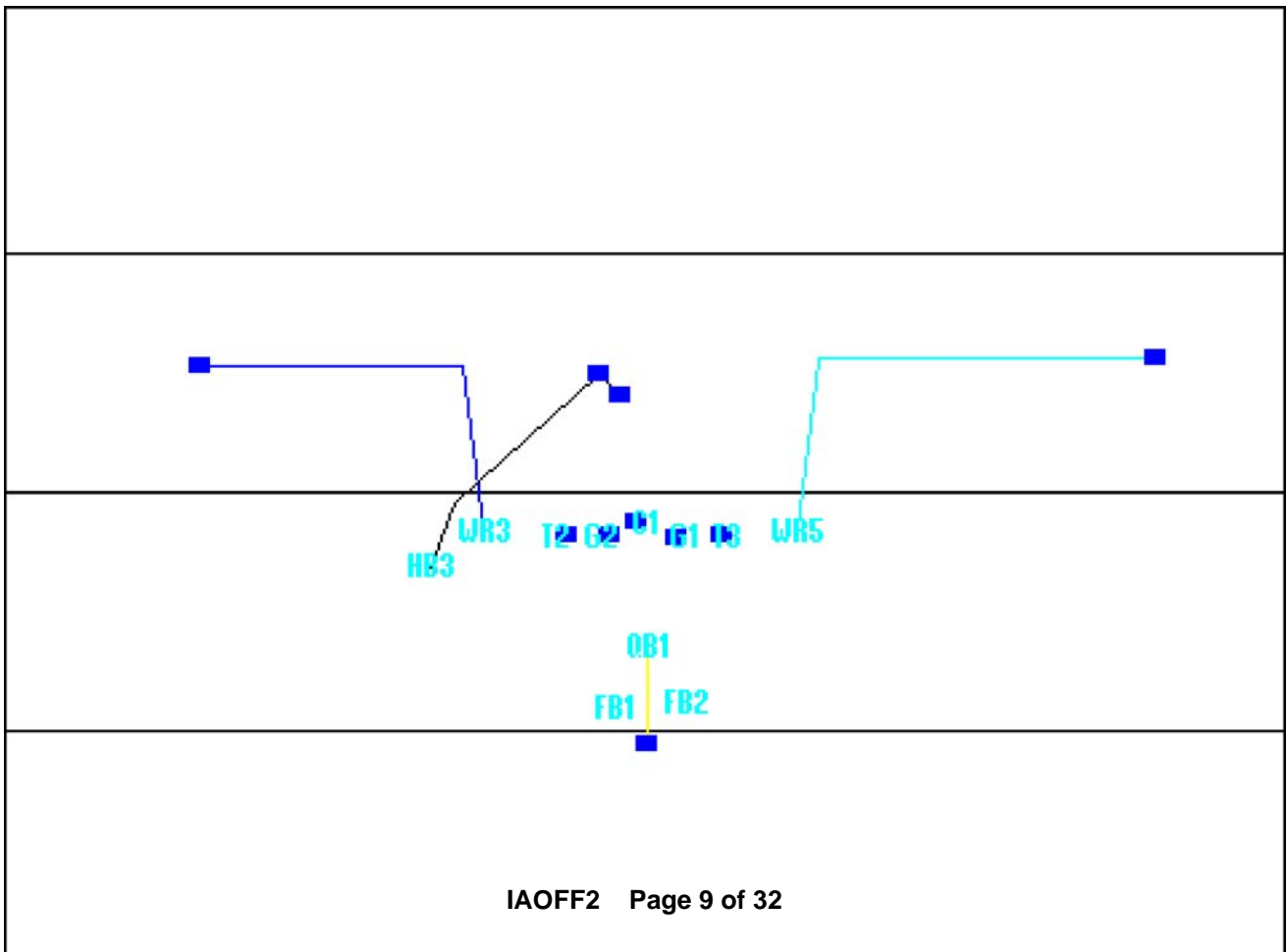
4-4 - RMAZA - RUN MID.



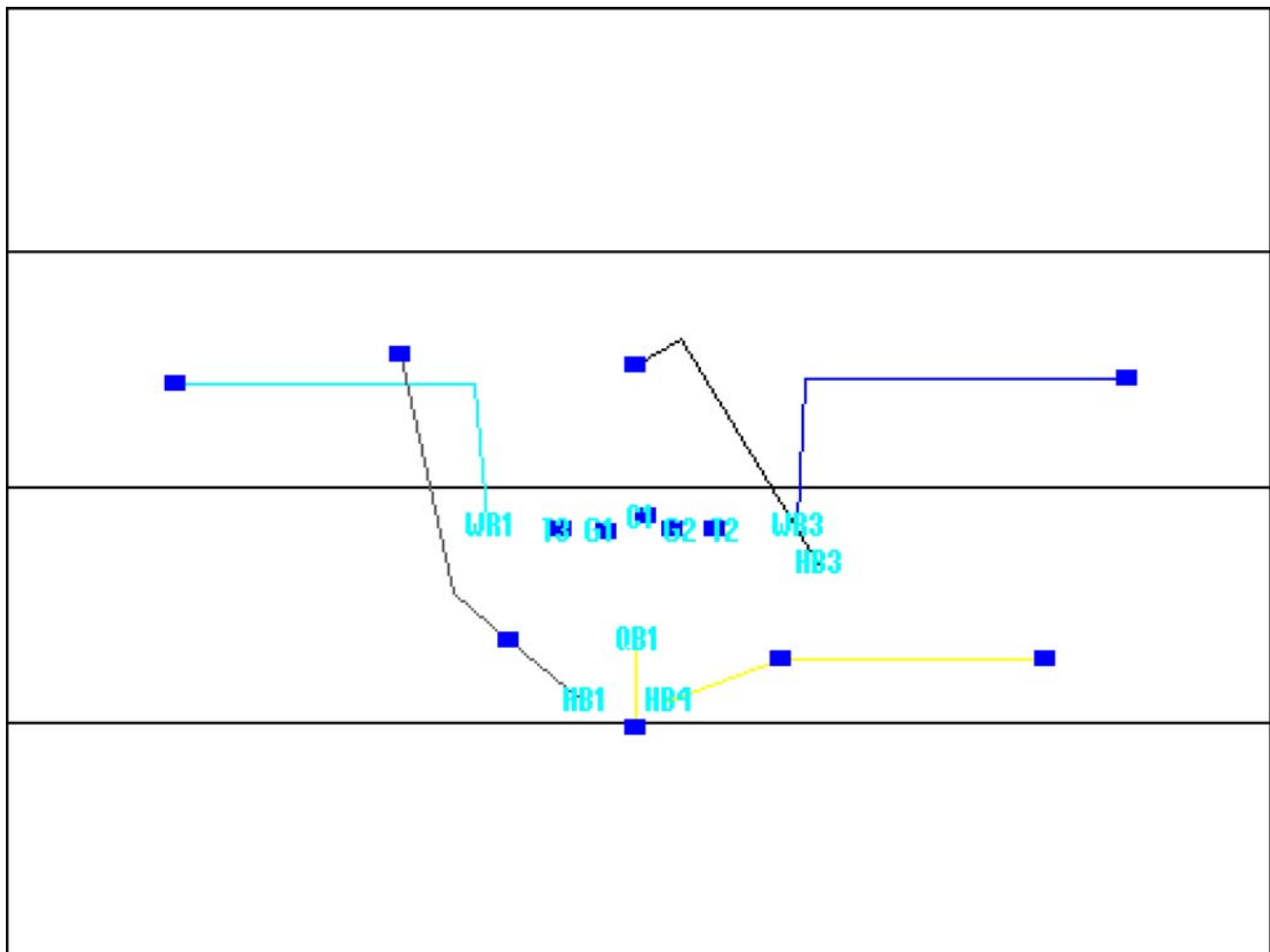
5-1 - GLPZAZB - GOAL LINE PASS



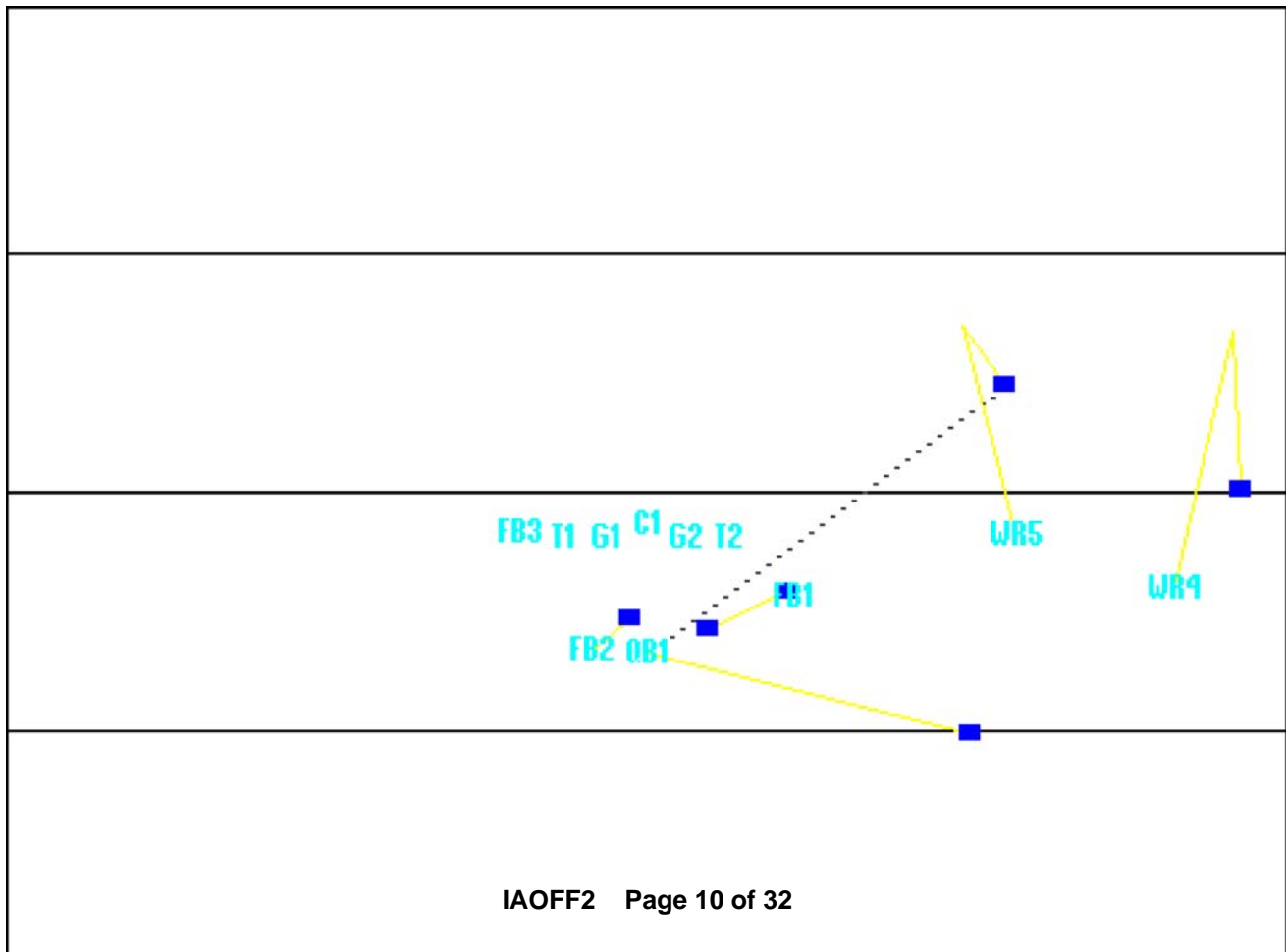
5-2 - GLP1 - GOAL LINE PASS



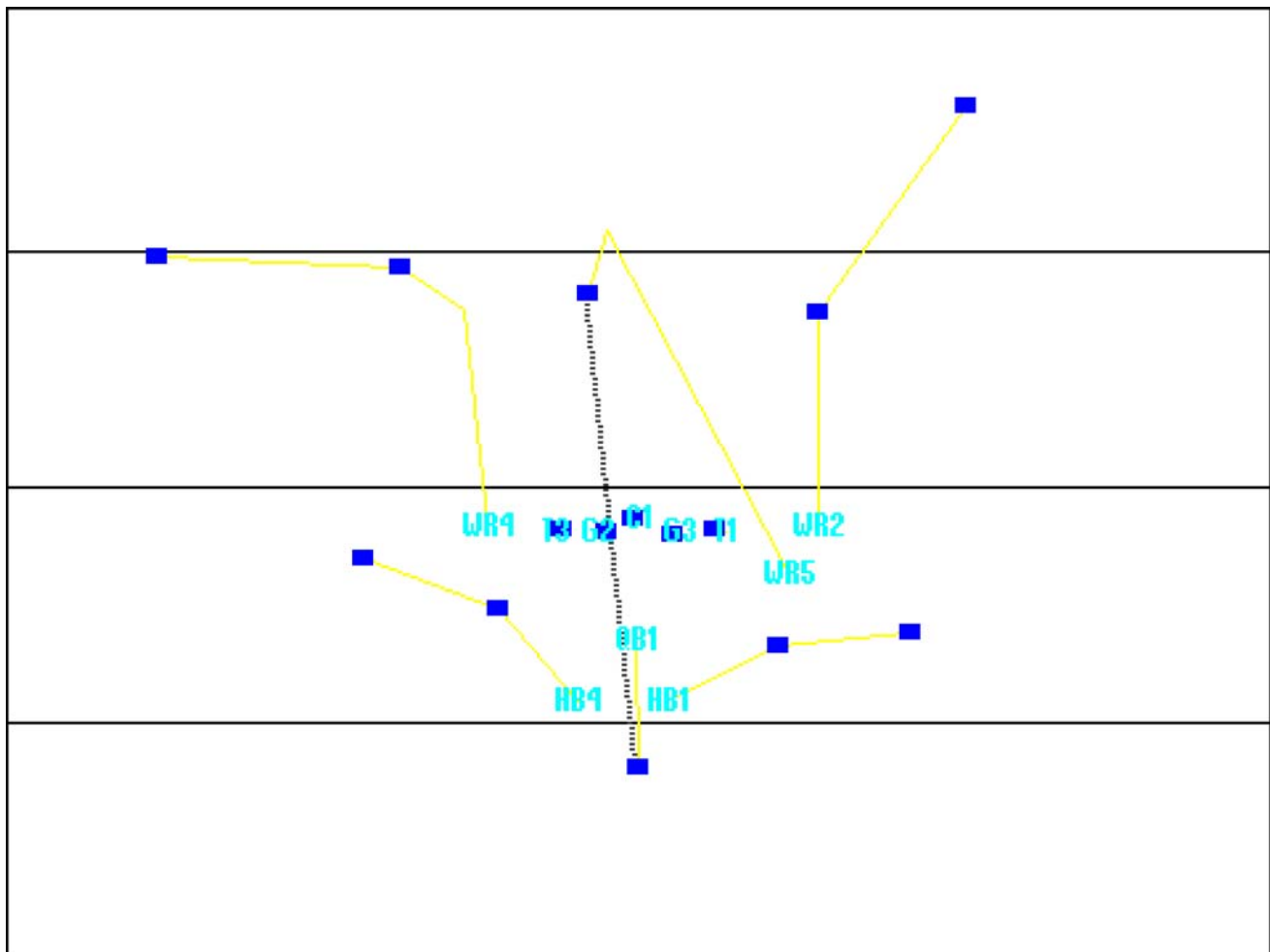
5-3 - GLP1z - GOAL LINE PASS



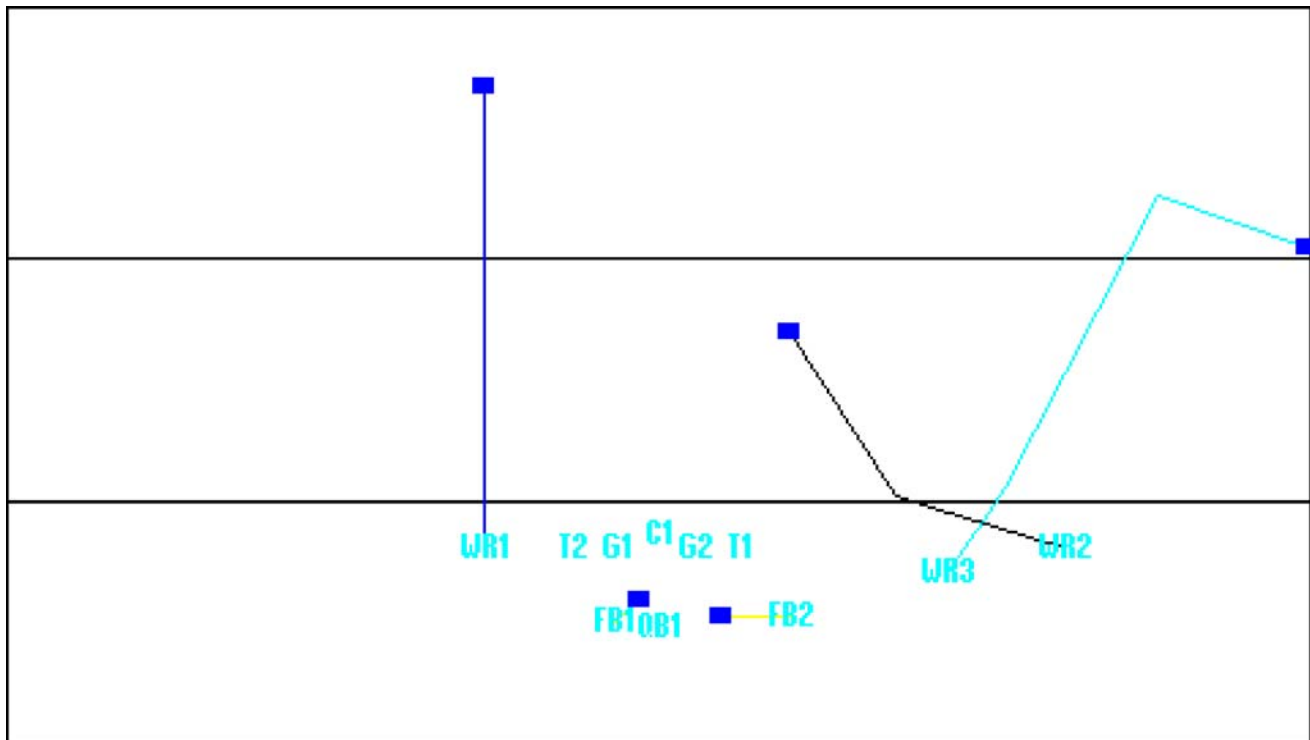
5-4 - GLPZAZA - GOAL LINE PASS



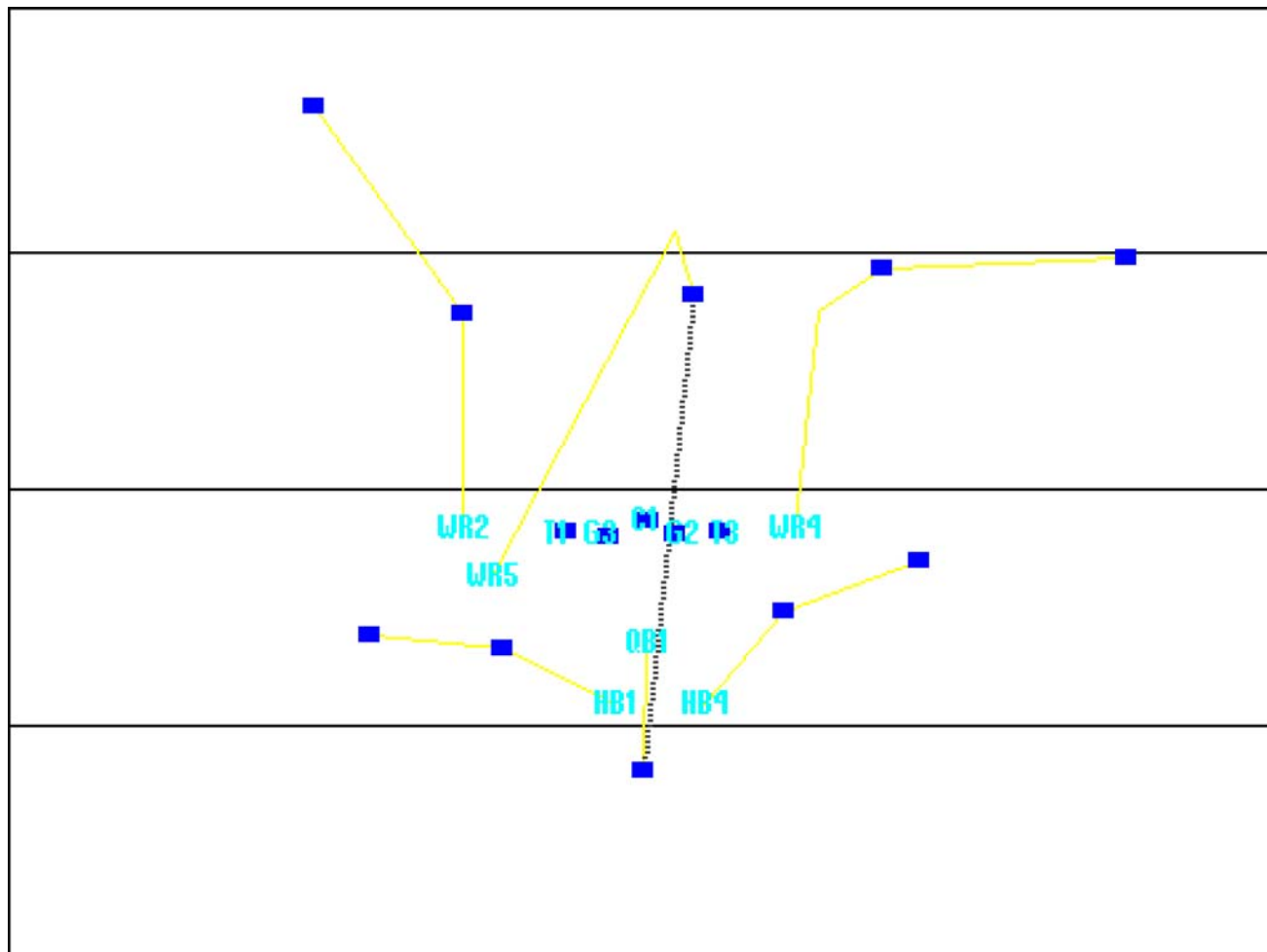
6-1 - PSLM1L - PASS SHORT LEFT



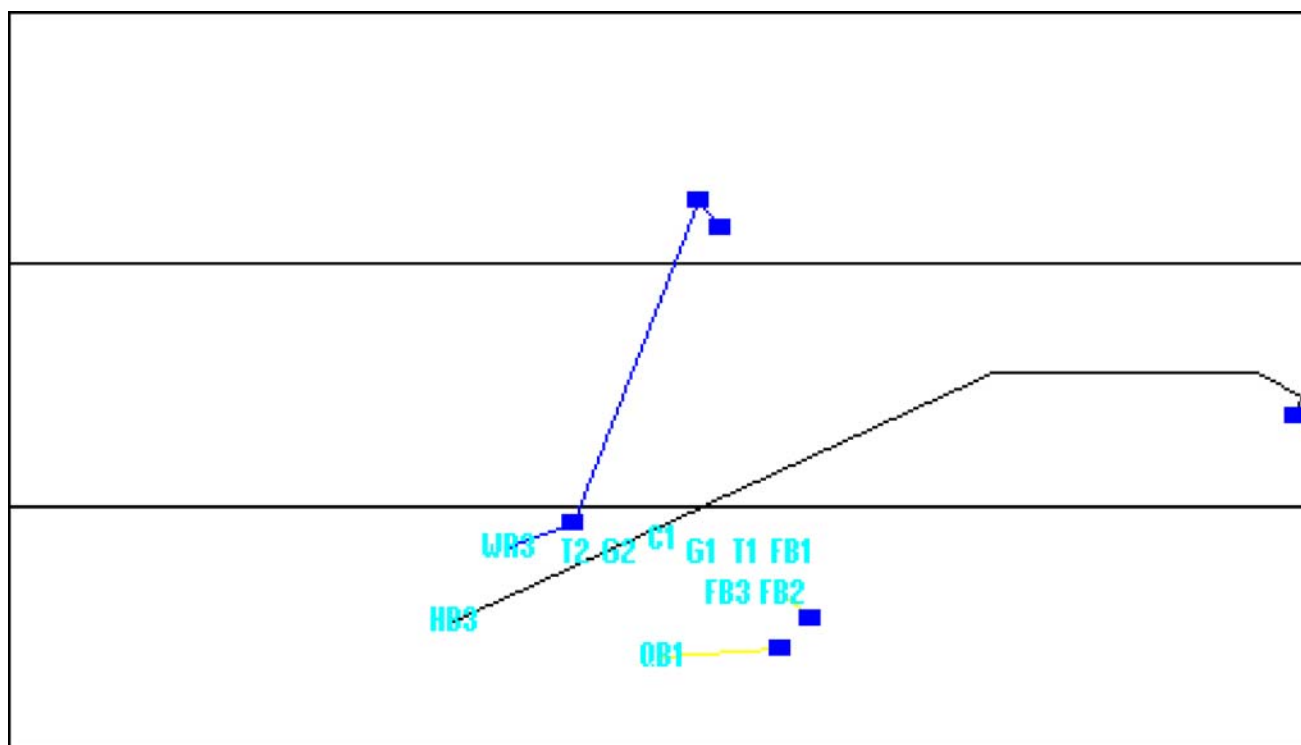
6-2 - PSLG11 - PASS SHORT LEFT



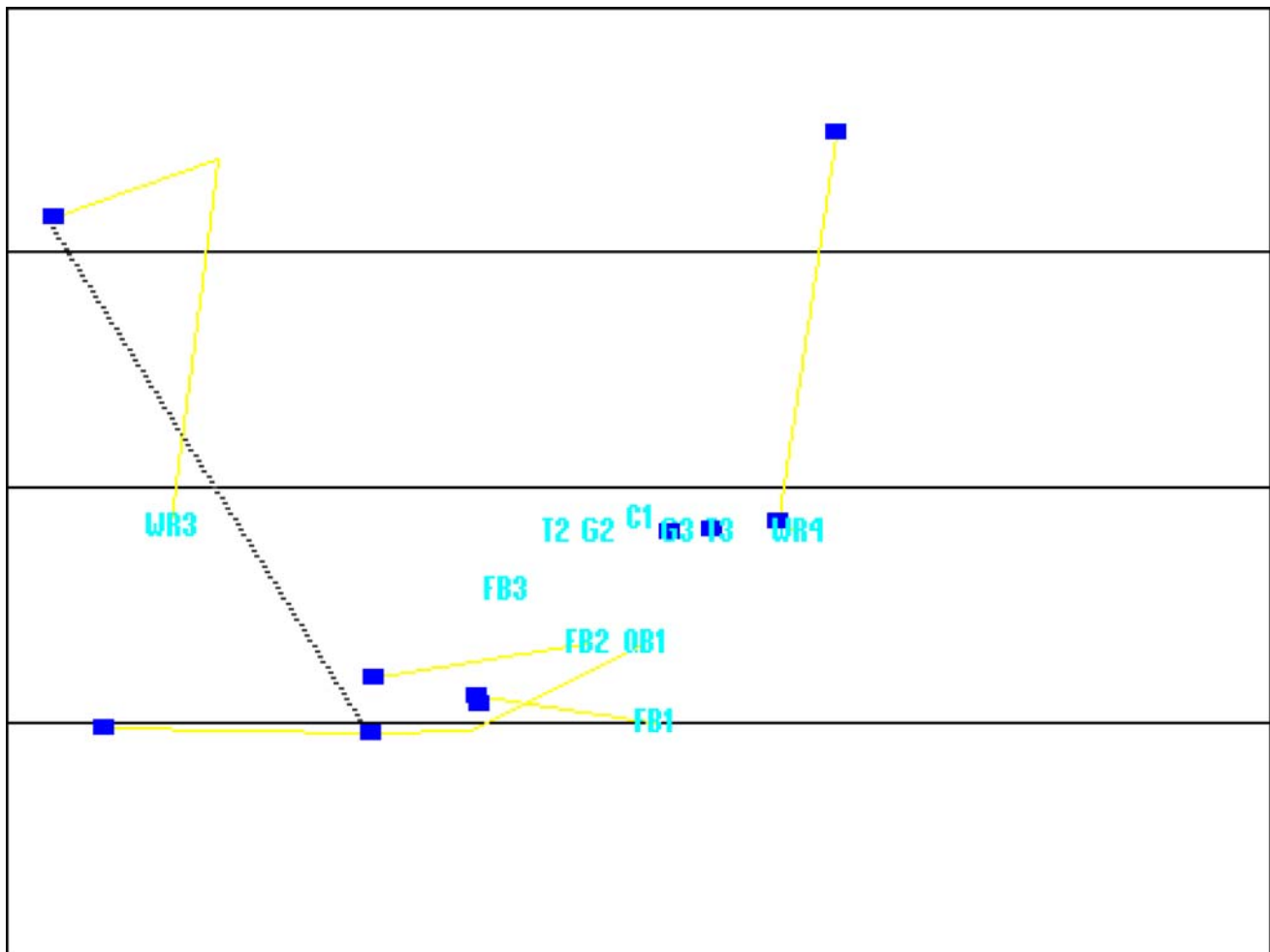
6-3 - PSLM1R - PASS SHORT LEFT



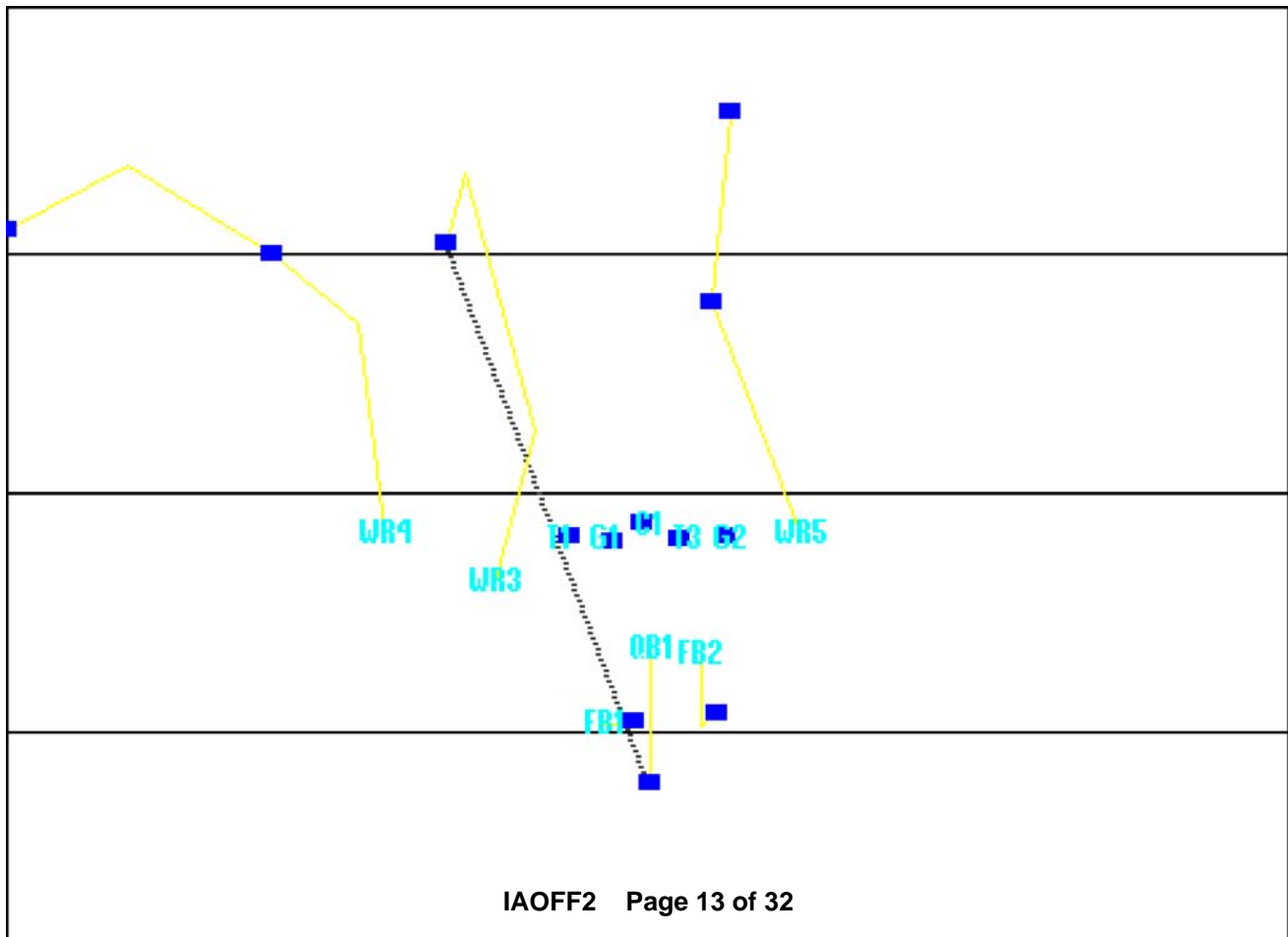
6-4 - PSLB34 - PASS SHORT LEFT



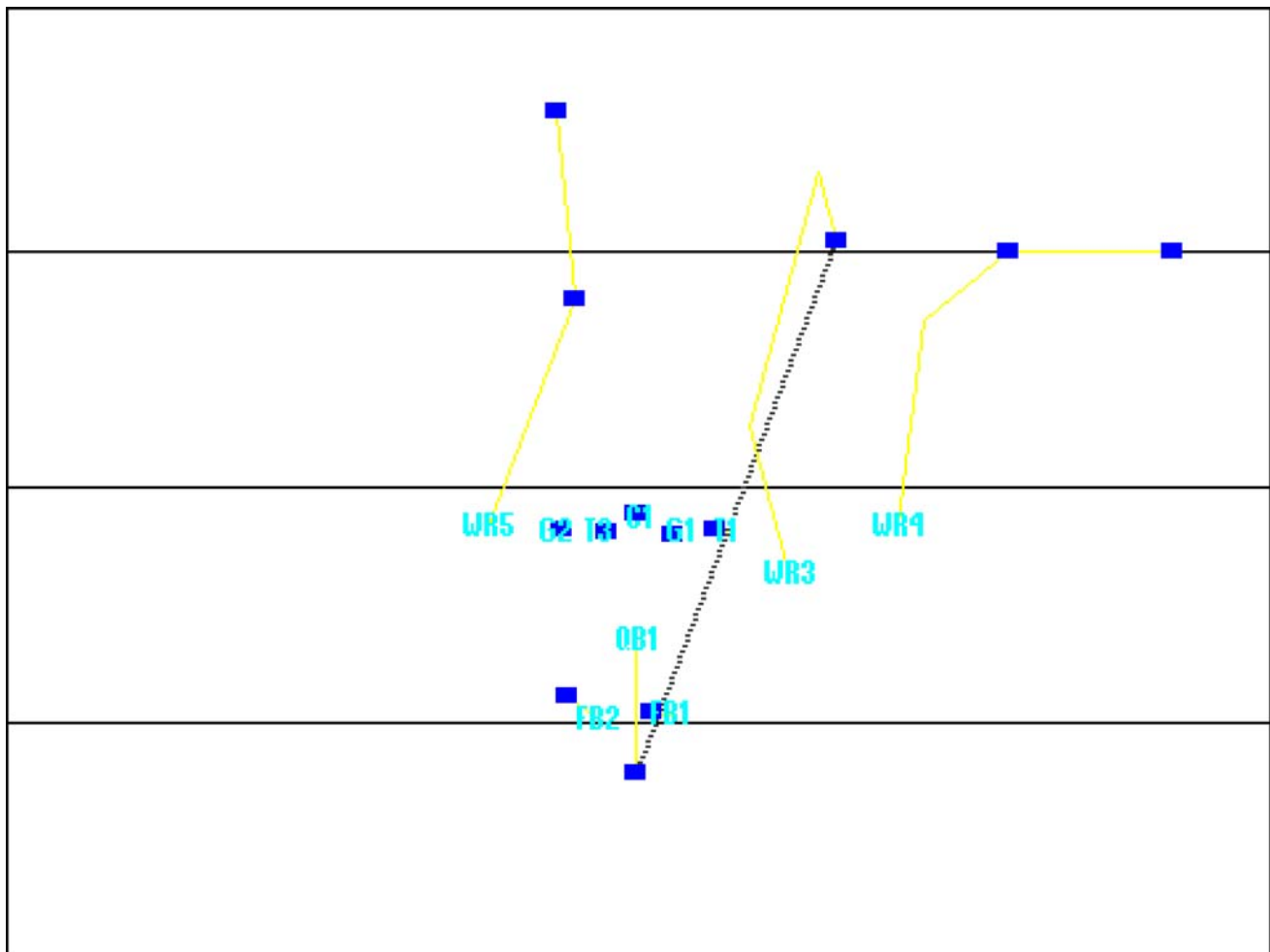
7-1 - PMRNew - PASS MED. RIGHT



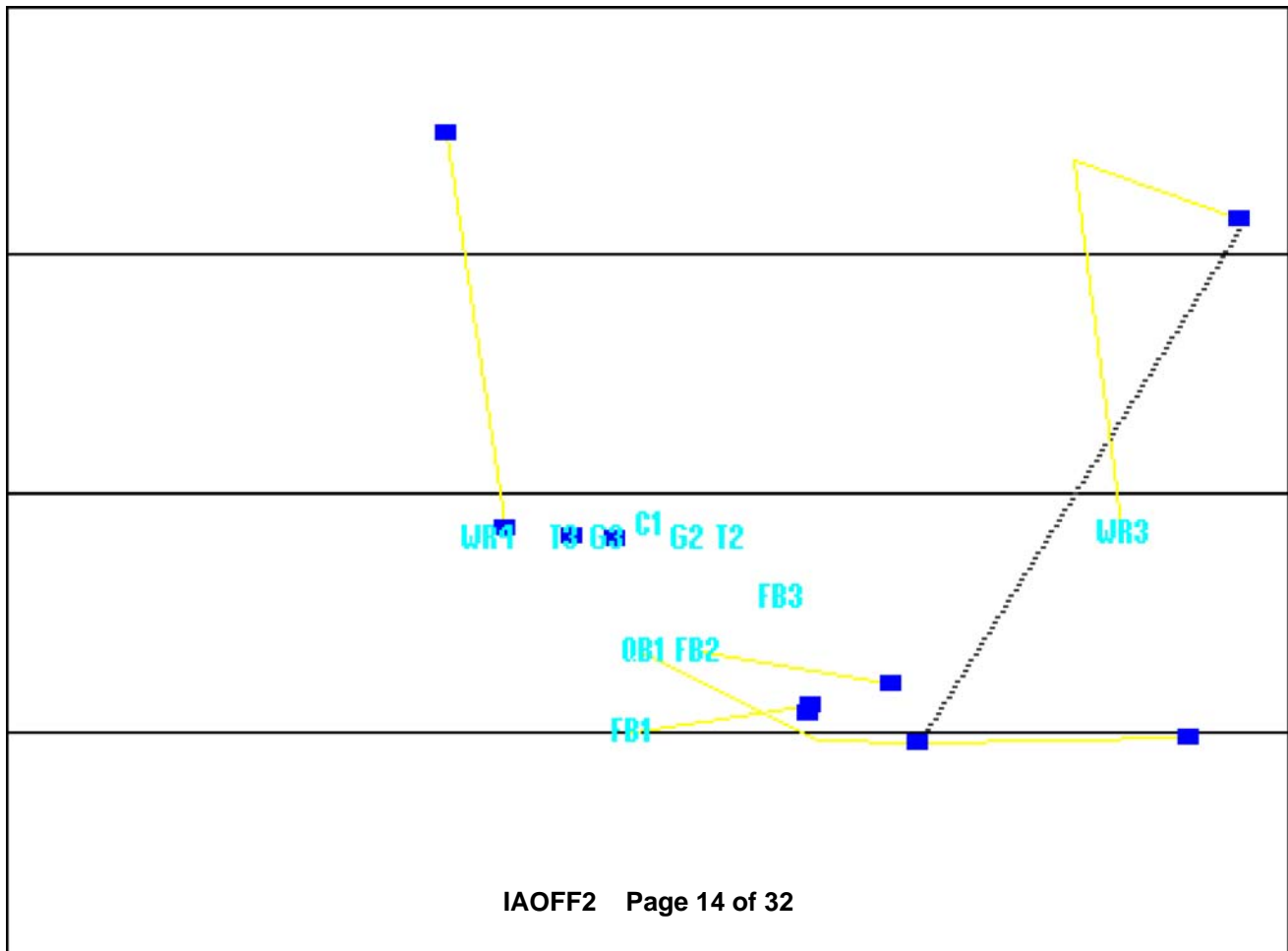
7-2 - PMRLLP4 - PASS MED. RIGHT



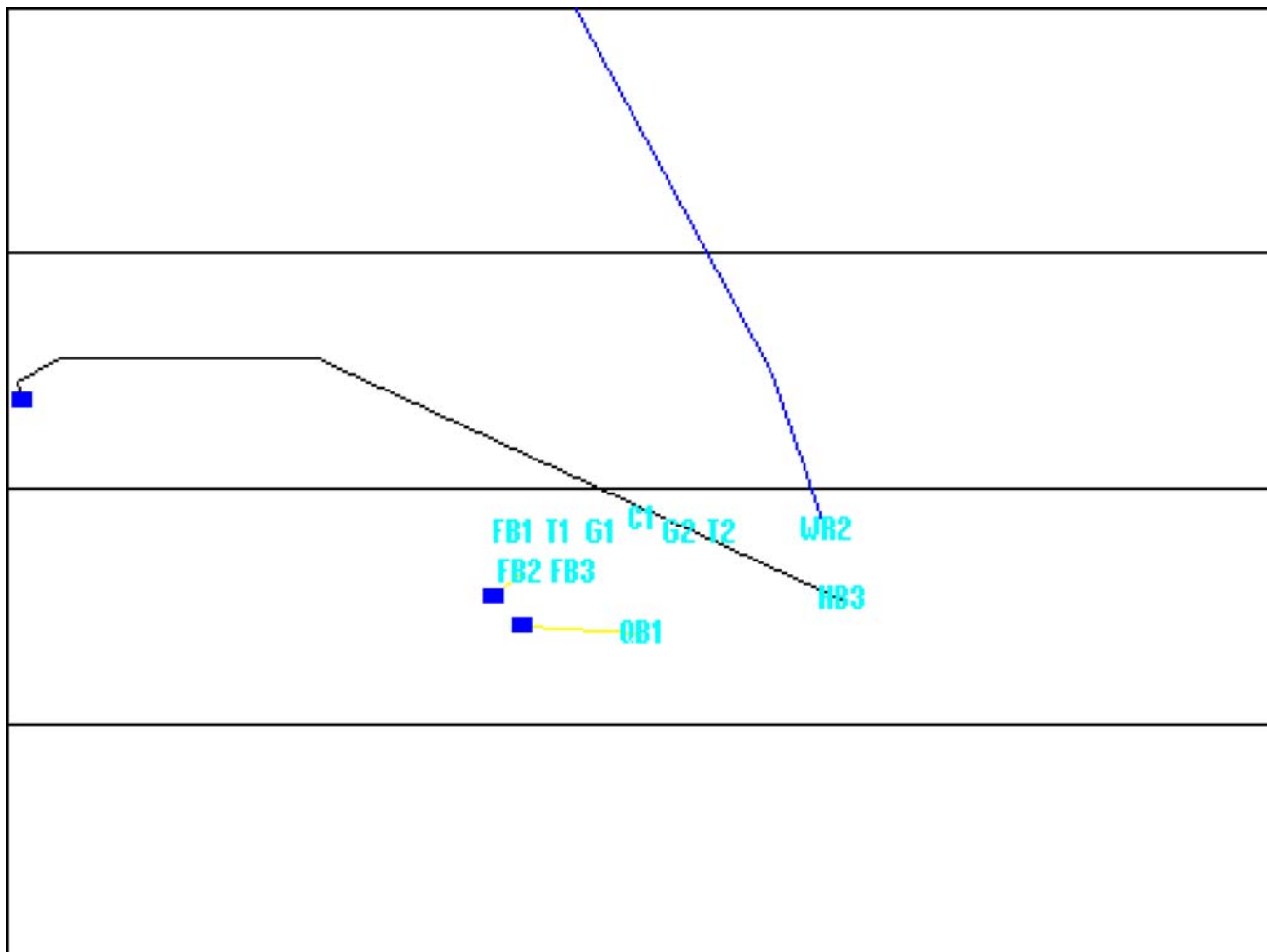
7-3 - PMRLLP3 - PASS MED. RIGHT



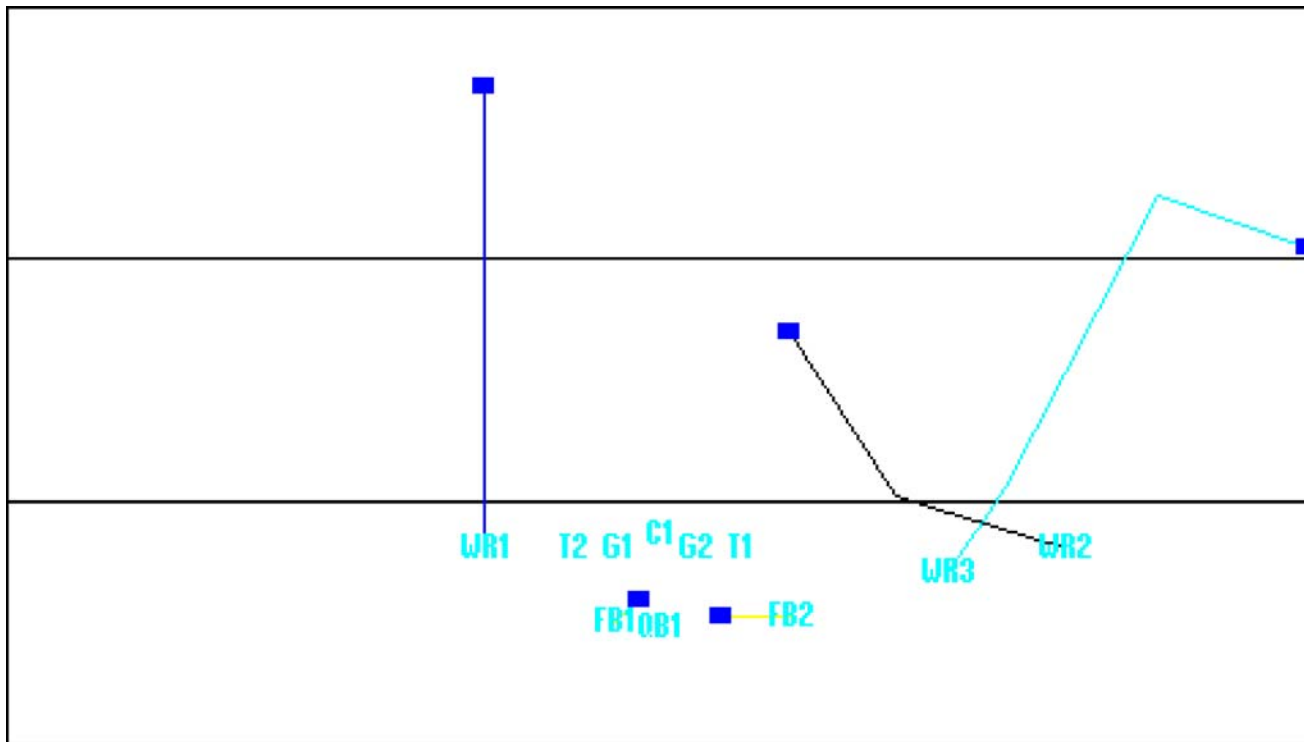
7-4 - PMRNew2 - PASS MED. RIGHT



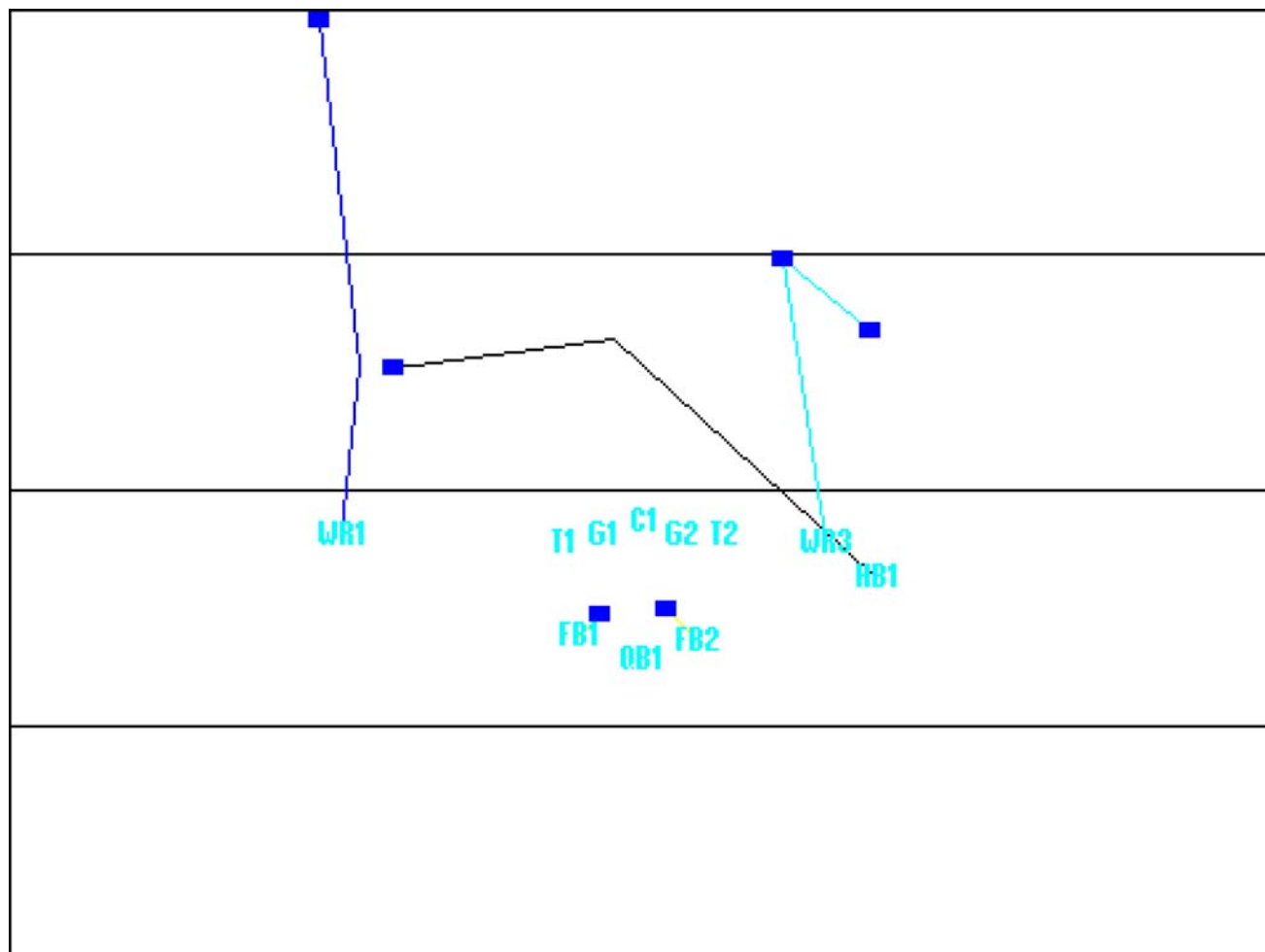
8-1 - PSMHB4z - PASS SHORT MID.



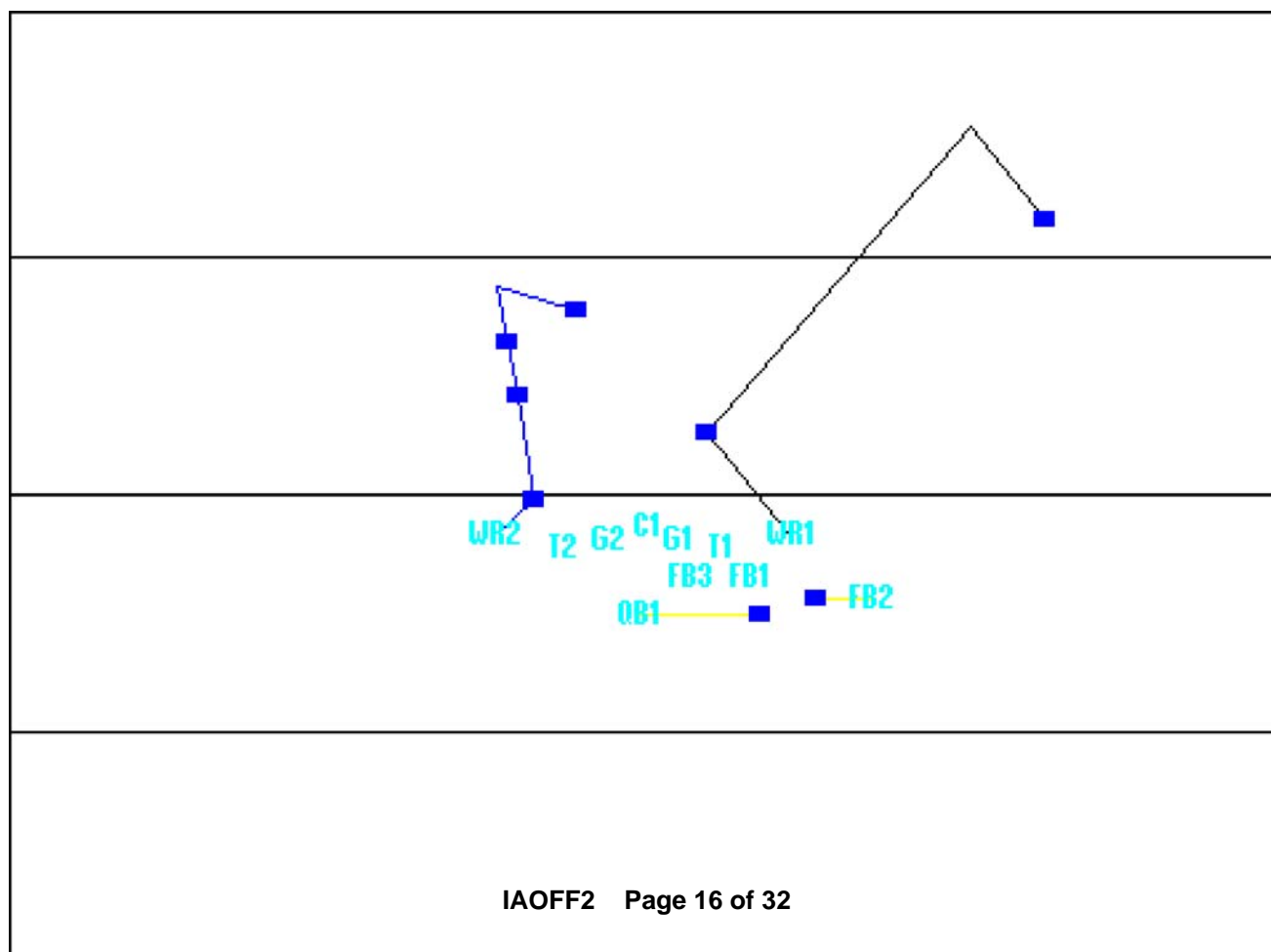
8-2 - PSMG11 - PASS SHORT MID.



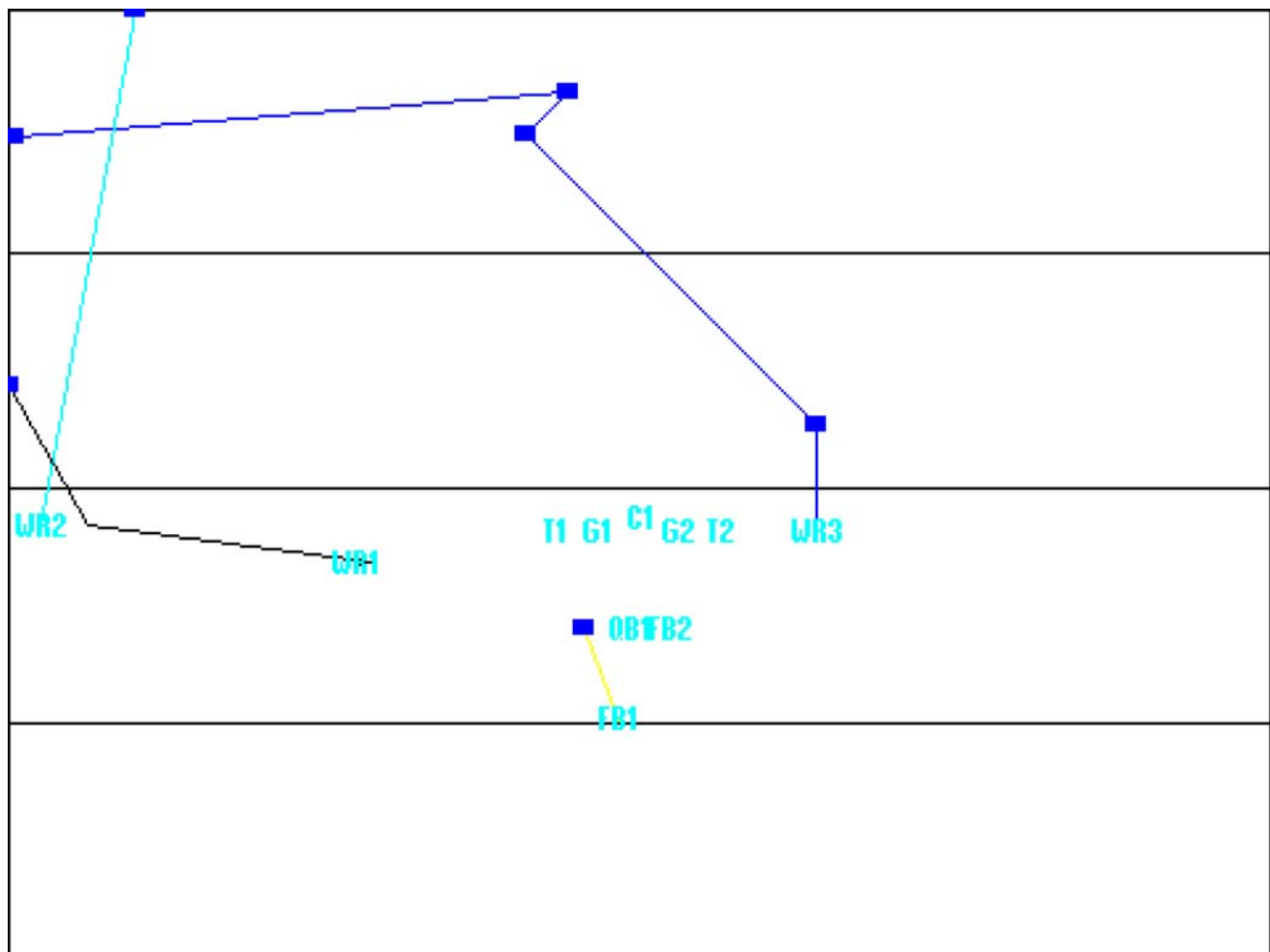
8-3 - PSMH1crs - PASS SHORT MID.



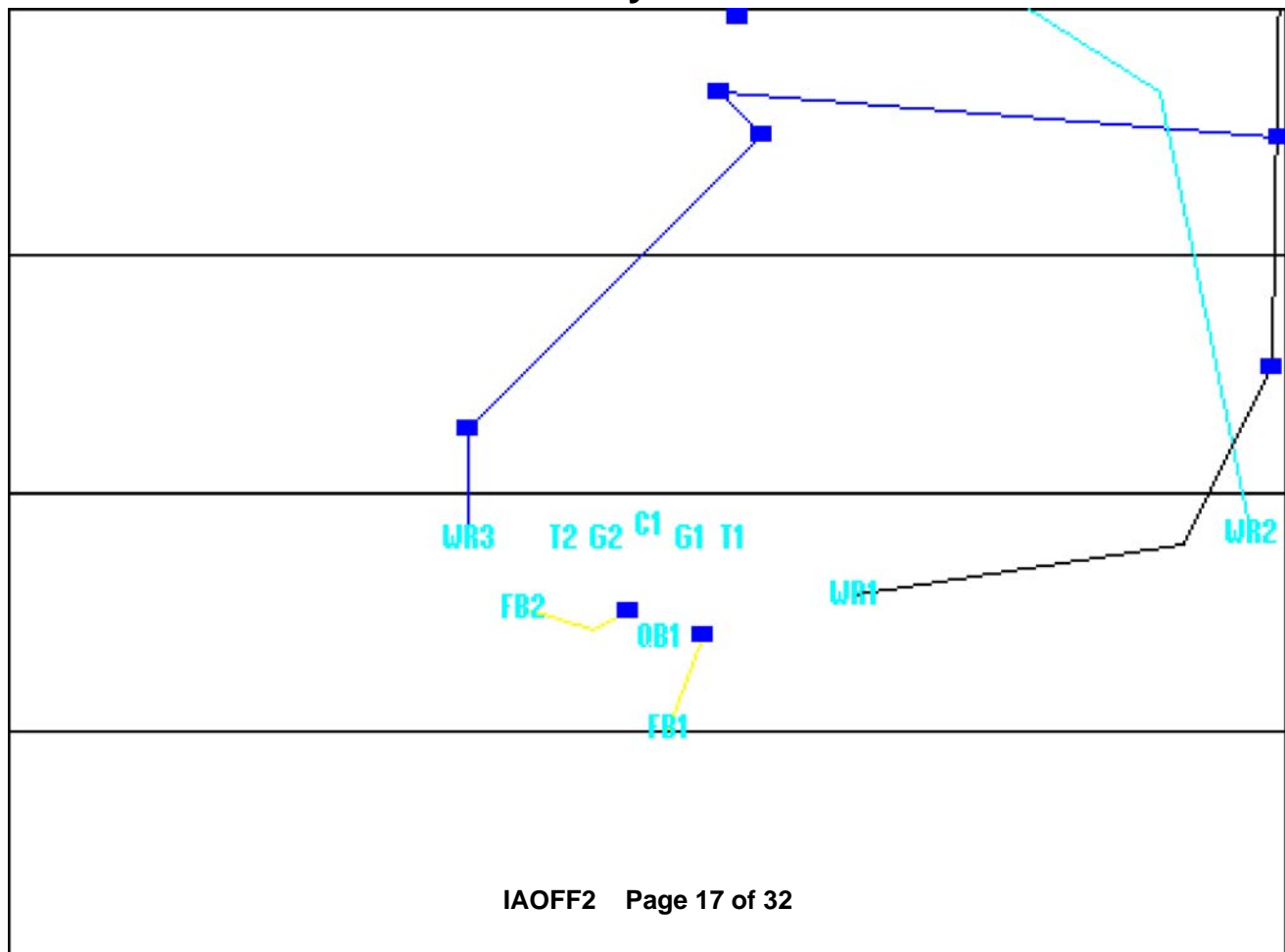
8-4 - PSMbk1x - PASS SHORT MID.



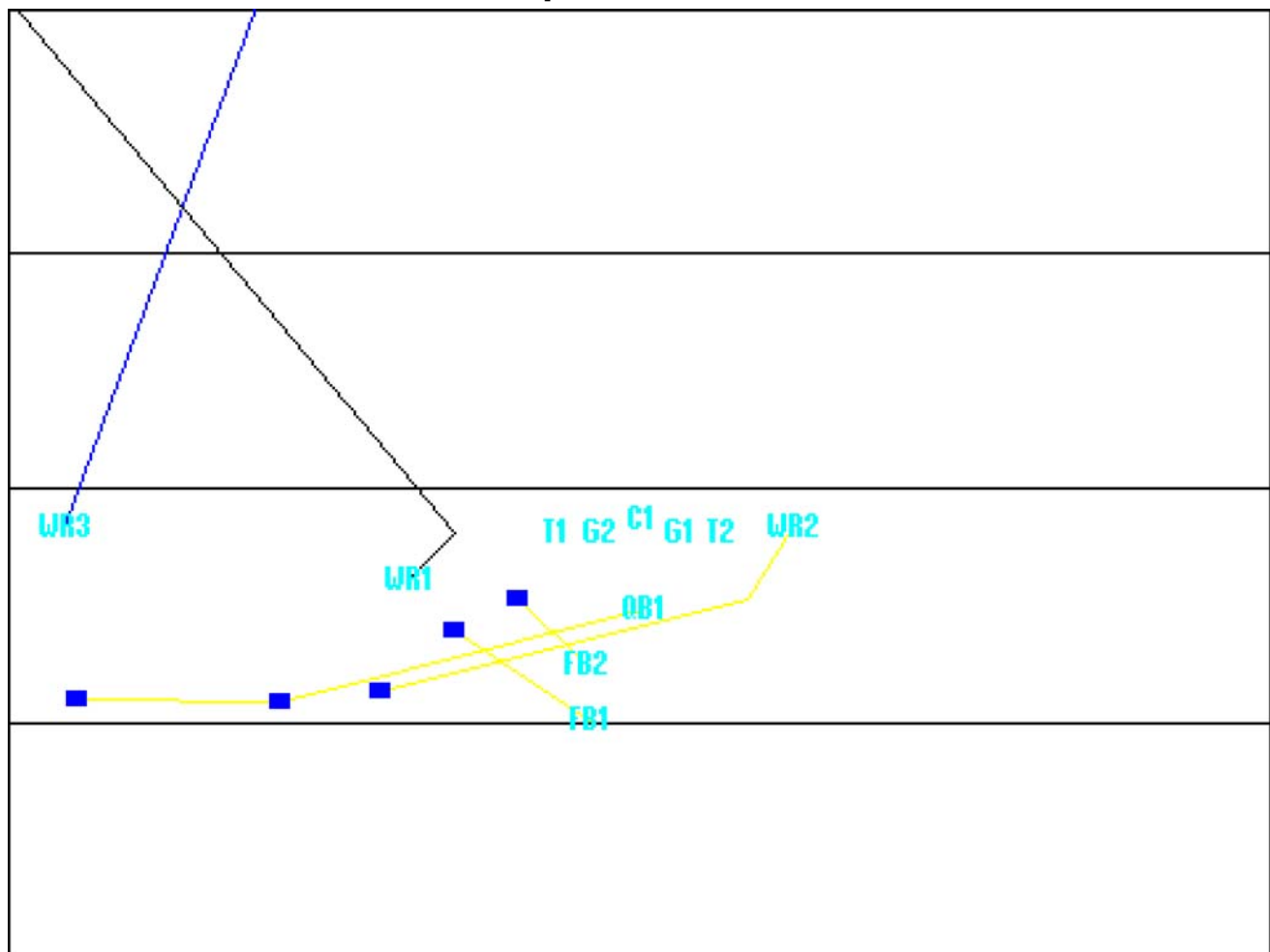
9-1 - PMLWR1 - PASS MED. LEFT



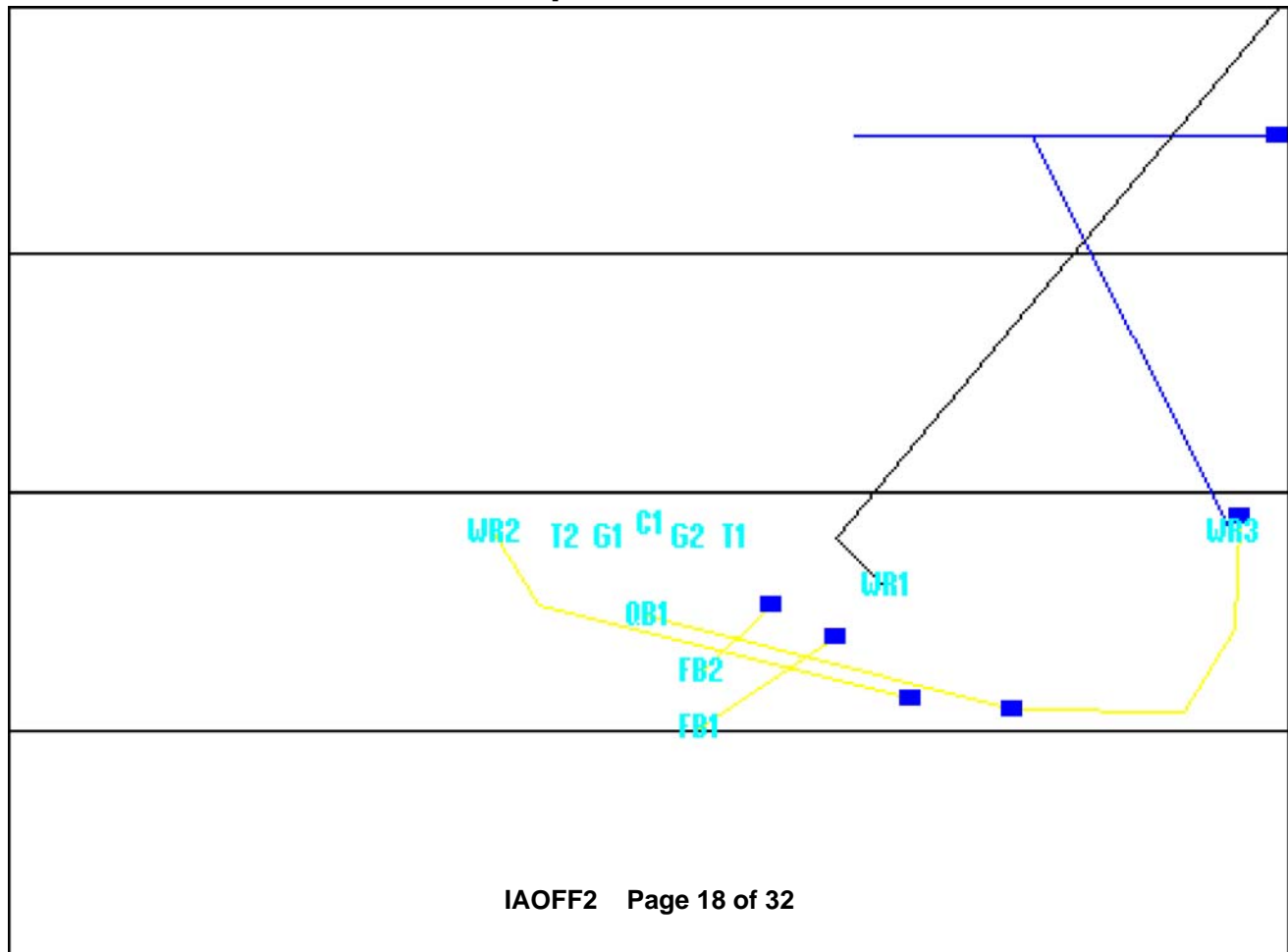
9-2 - PML2OT5y - PASS MED. LEFT



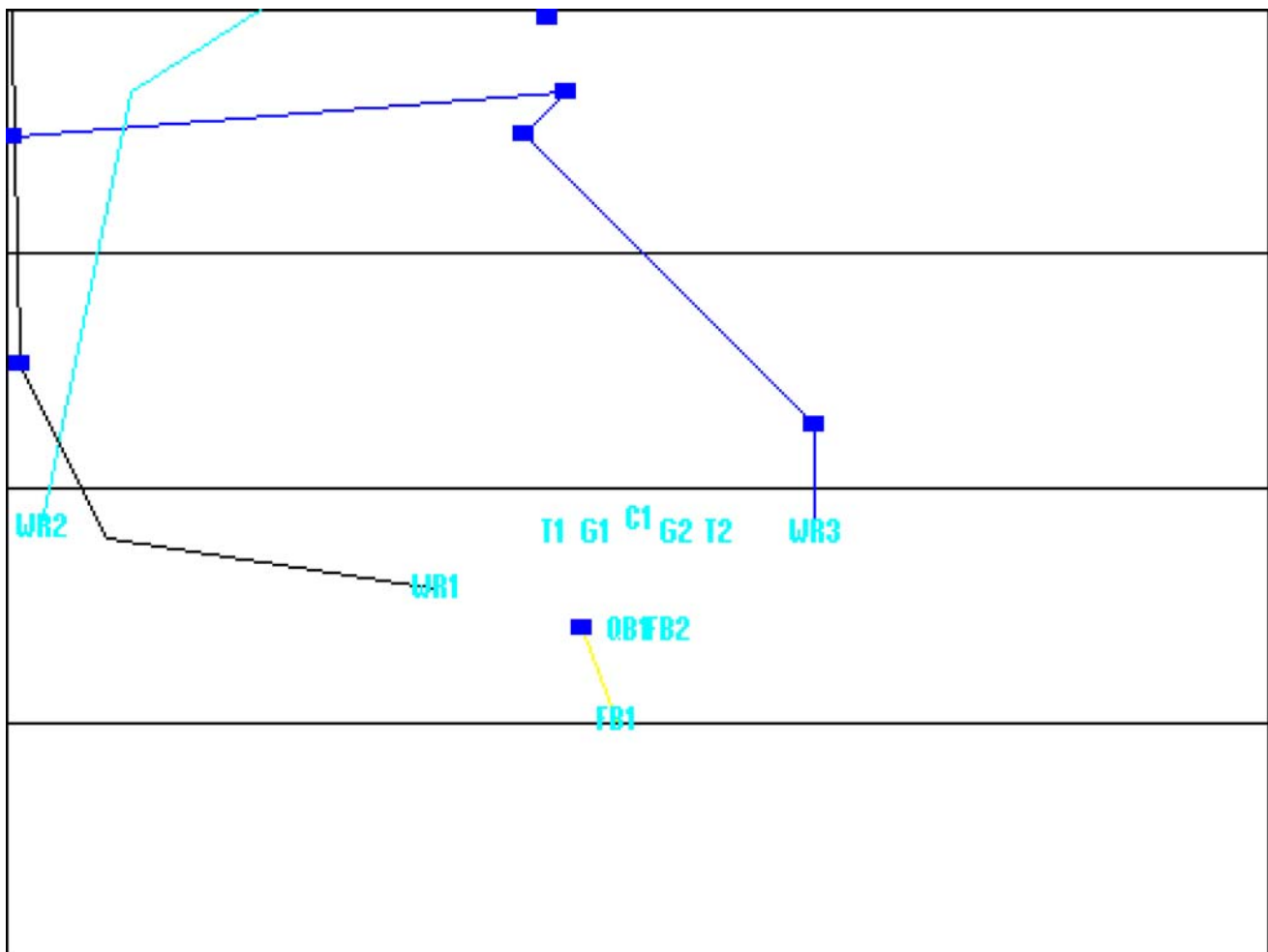
9-3 - PMLp2z - PASS MED. LEFT



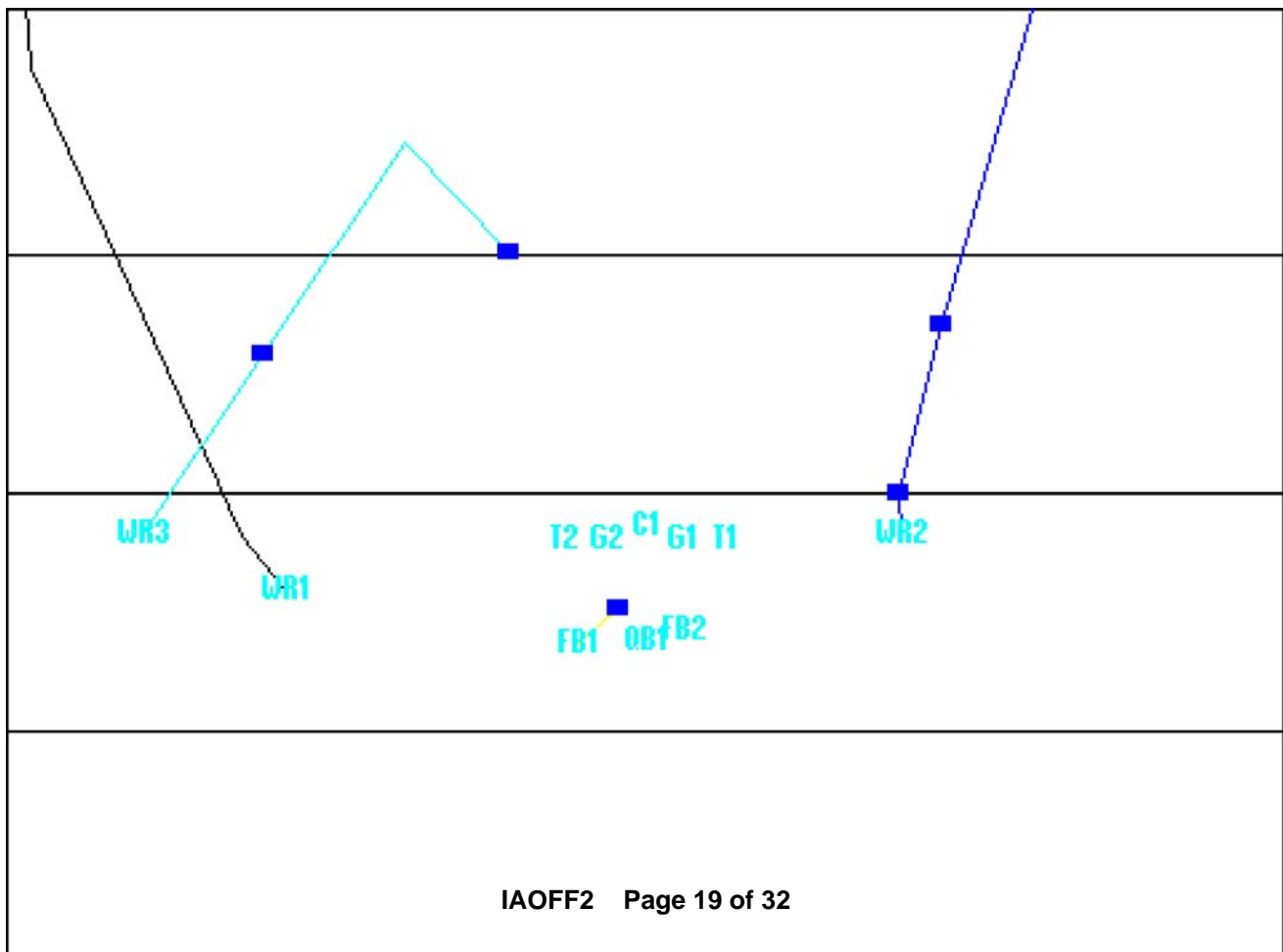
9-4 - PMLp2a - PASS MED. LEFT



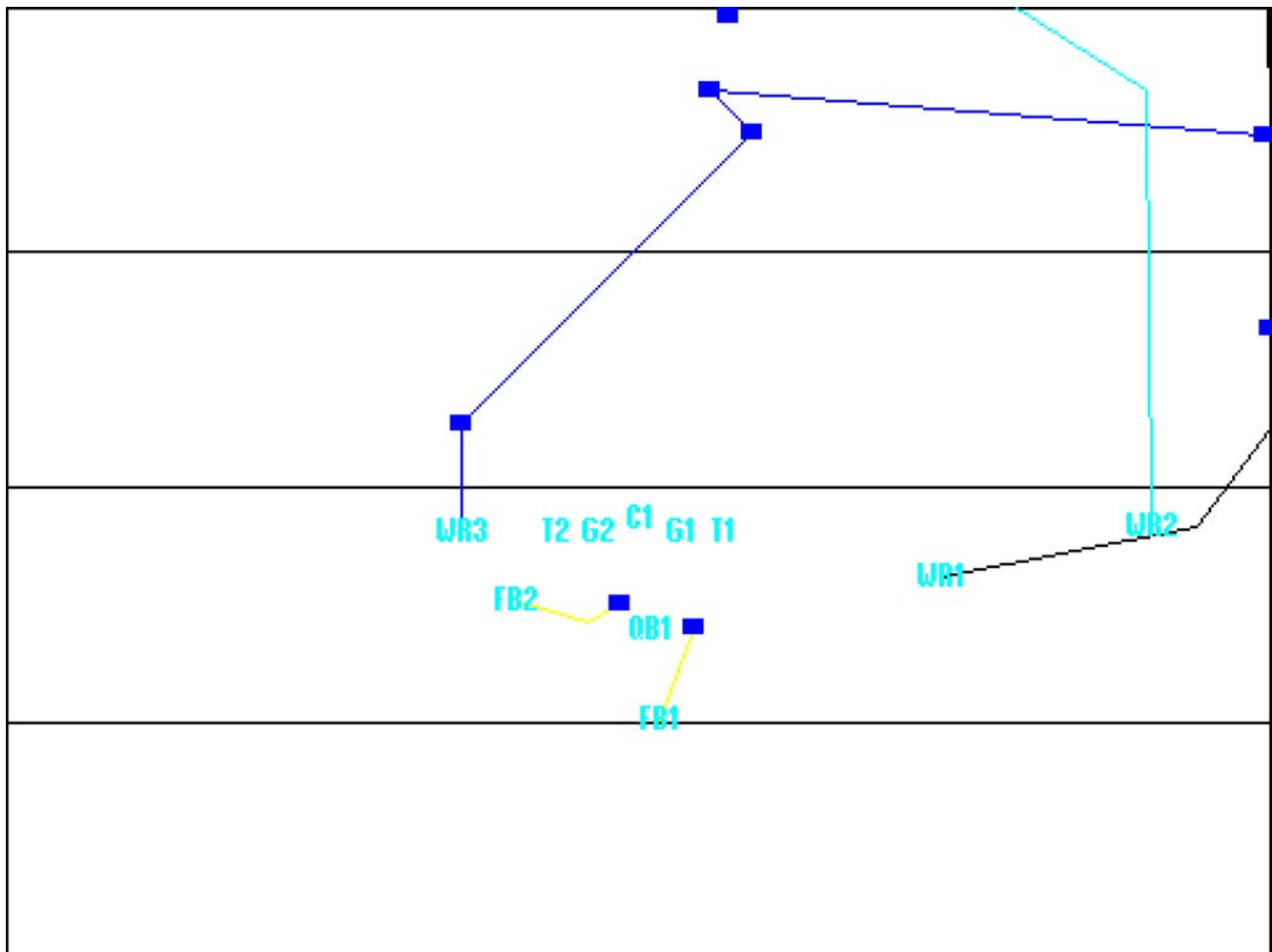
10-1 - PMMWR1 - PASS MED. MID.



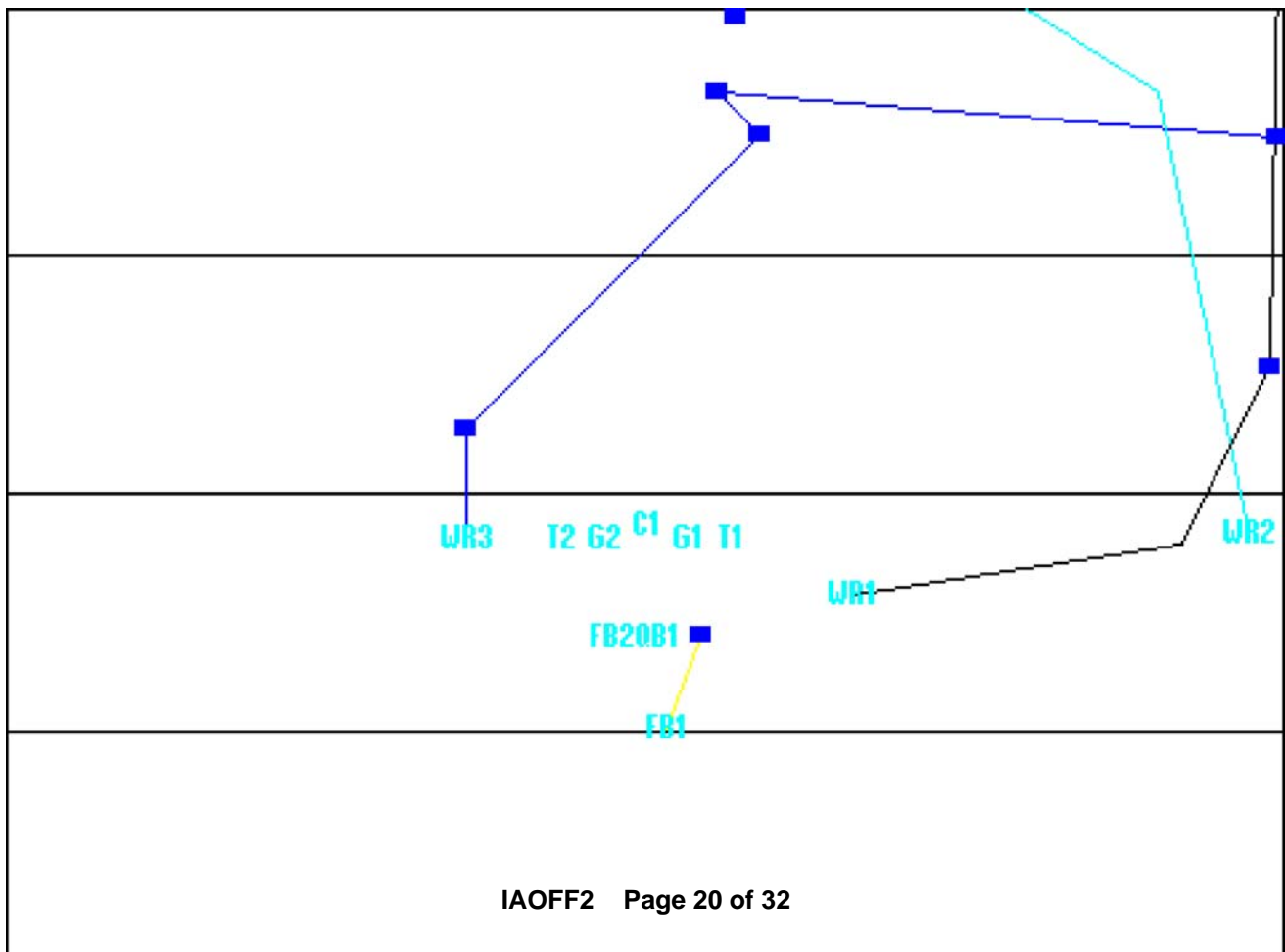
10-2 - PMMOLD1 - PASS MED. MID.



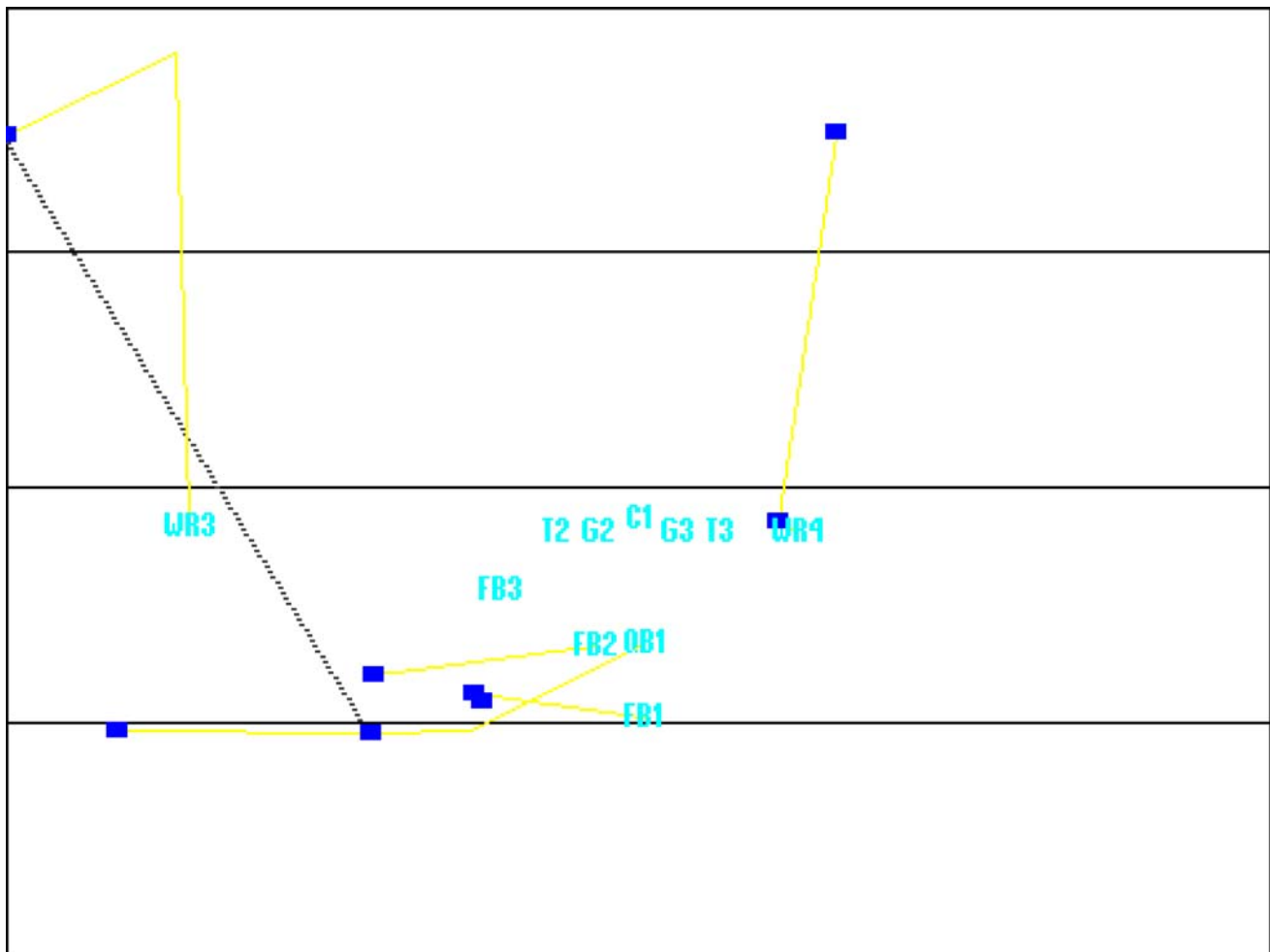
10-3 - PMM2Mov1 - PASS MED. MID.



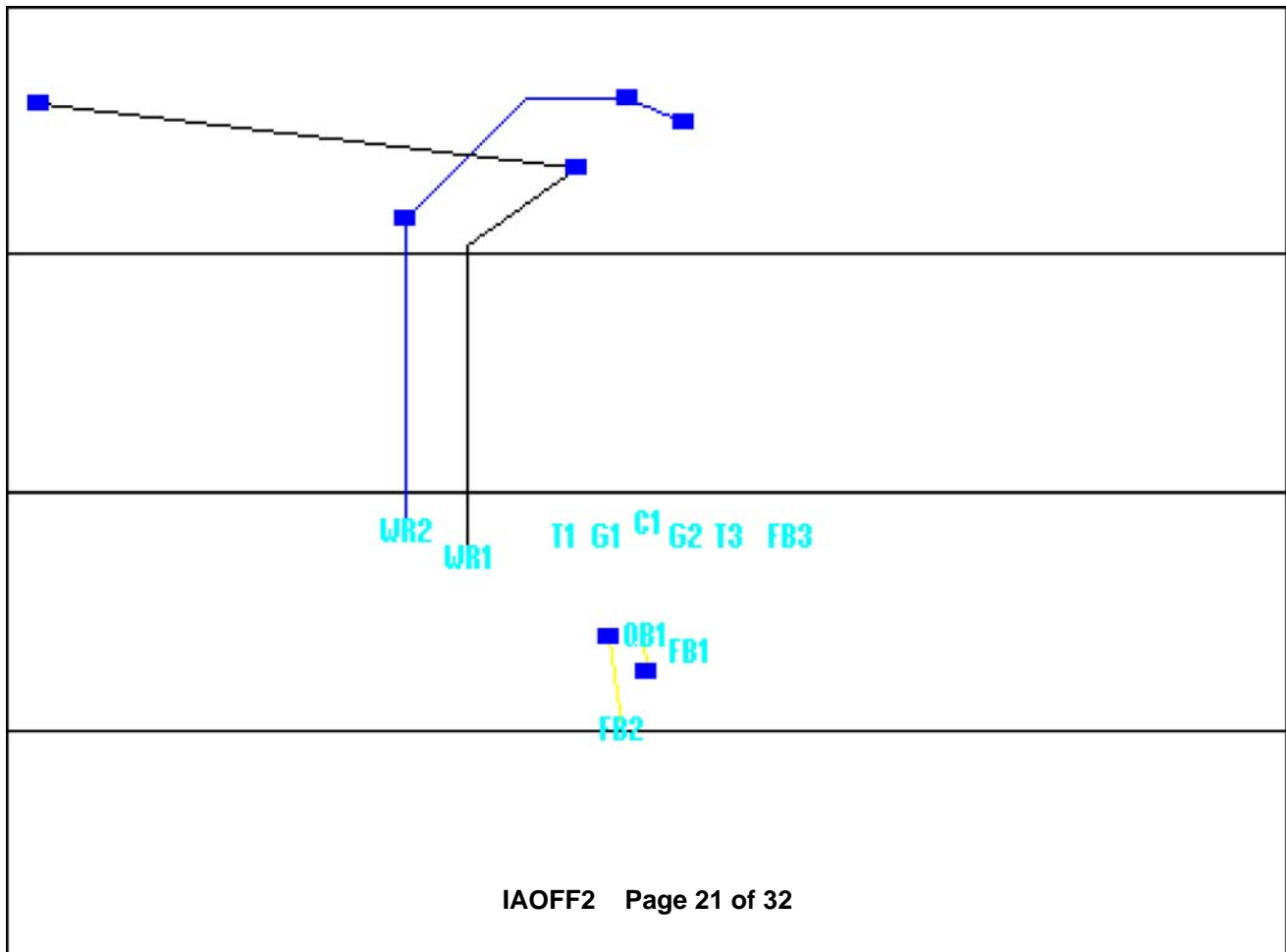
10-4 - PMMWR1b - PASS MED. MID.



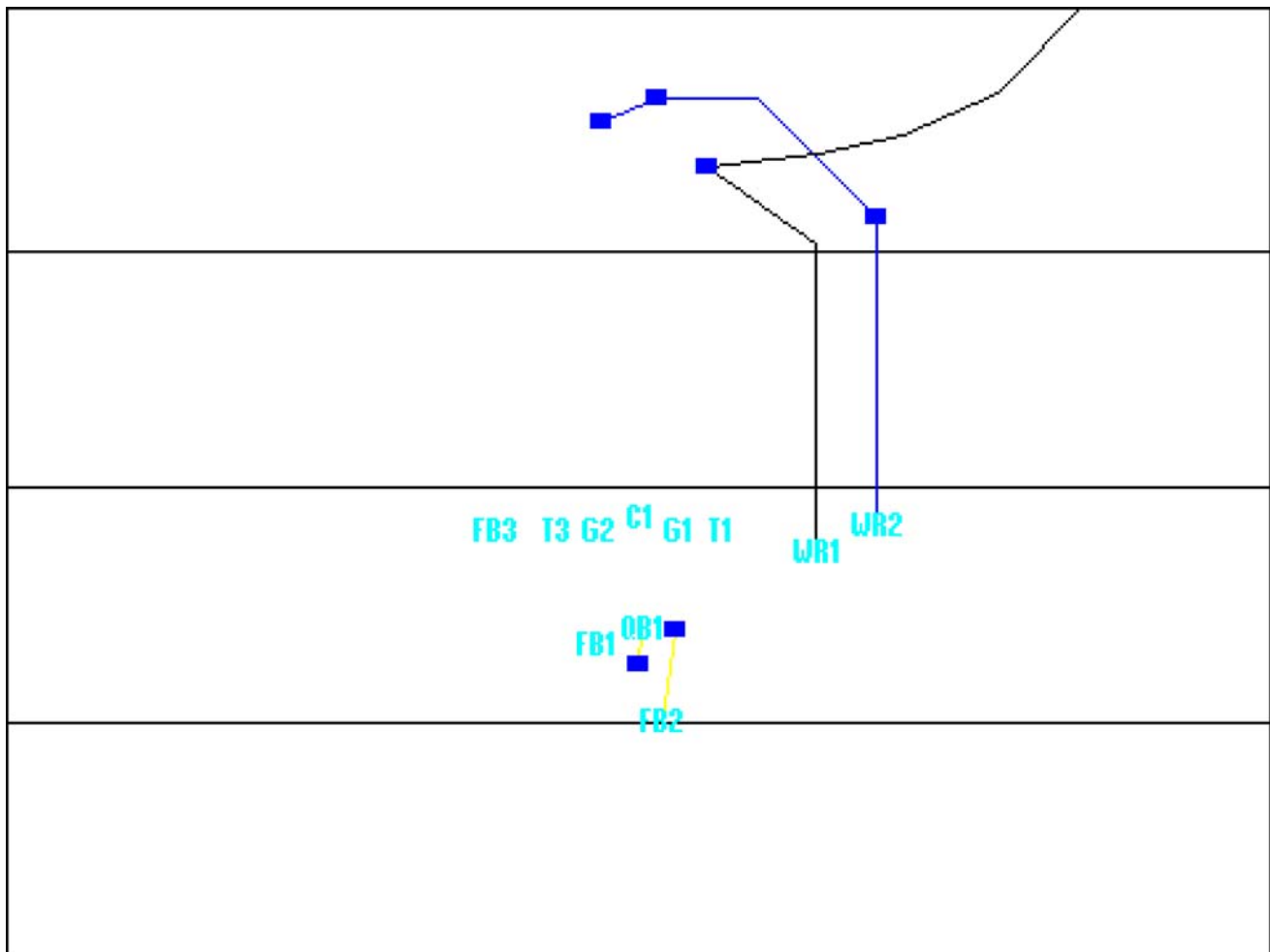
11-1 - PSRGBBA - PASS SHORT RIGHT



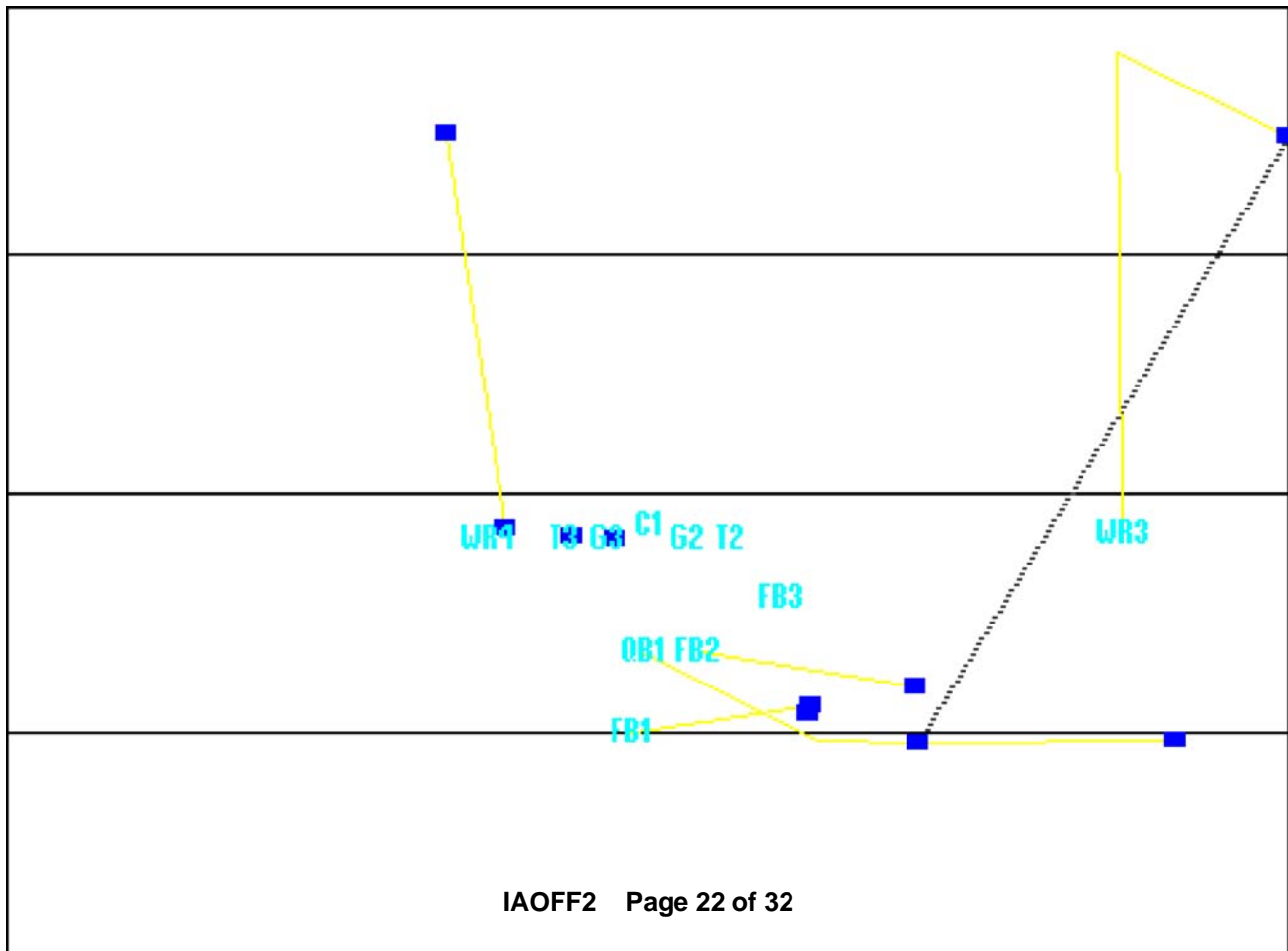
11-2 - PSRHAT11 - PASS SHORT RIGHT



11-3 - PSRHAT12 - PASS SHORT RIGHT

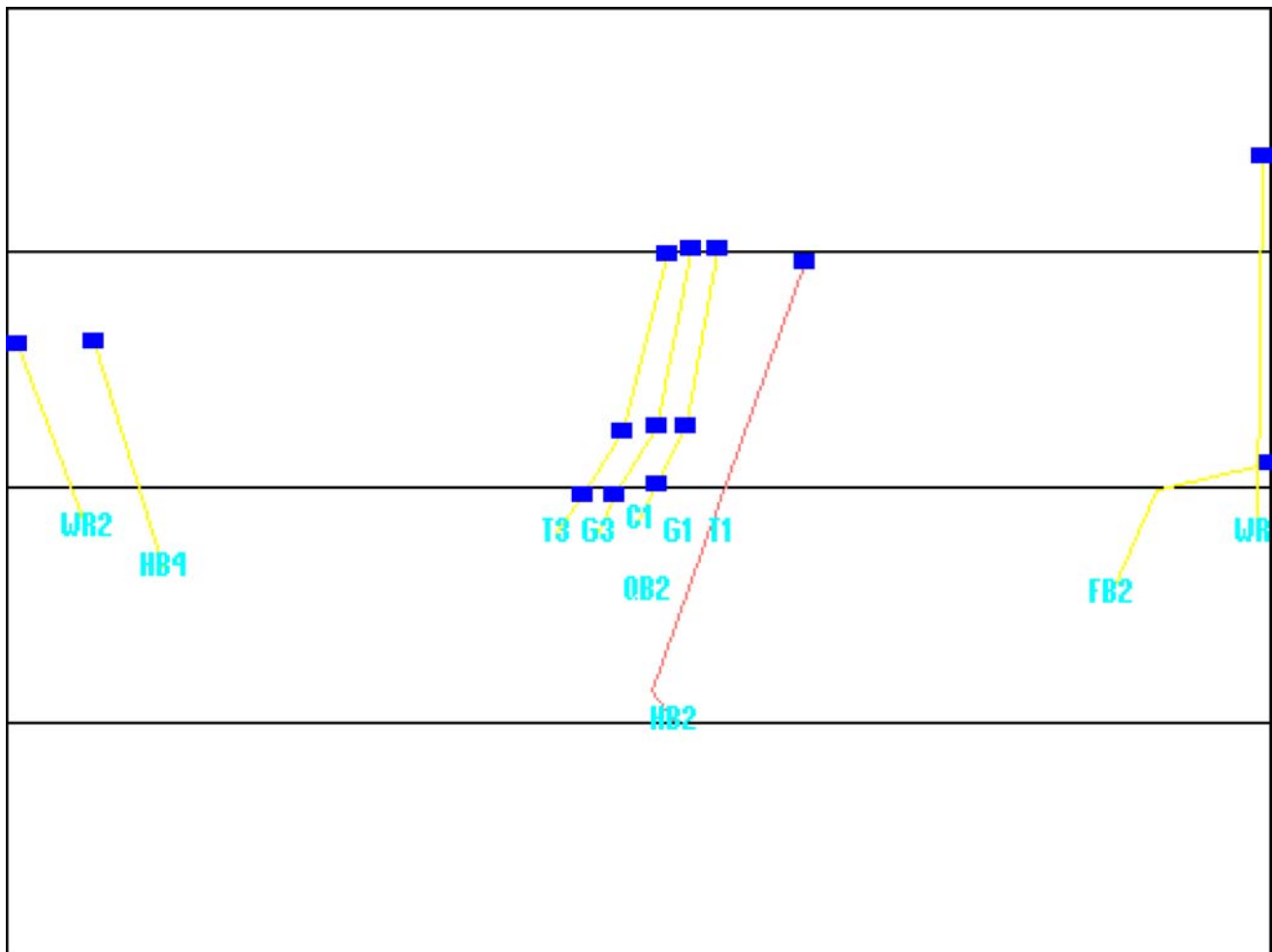


11-4 - PSRGBBD - PASS SHORT RIGHT

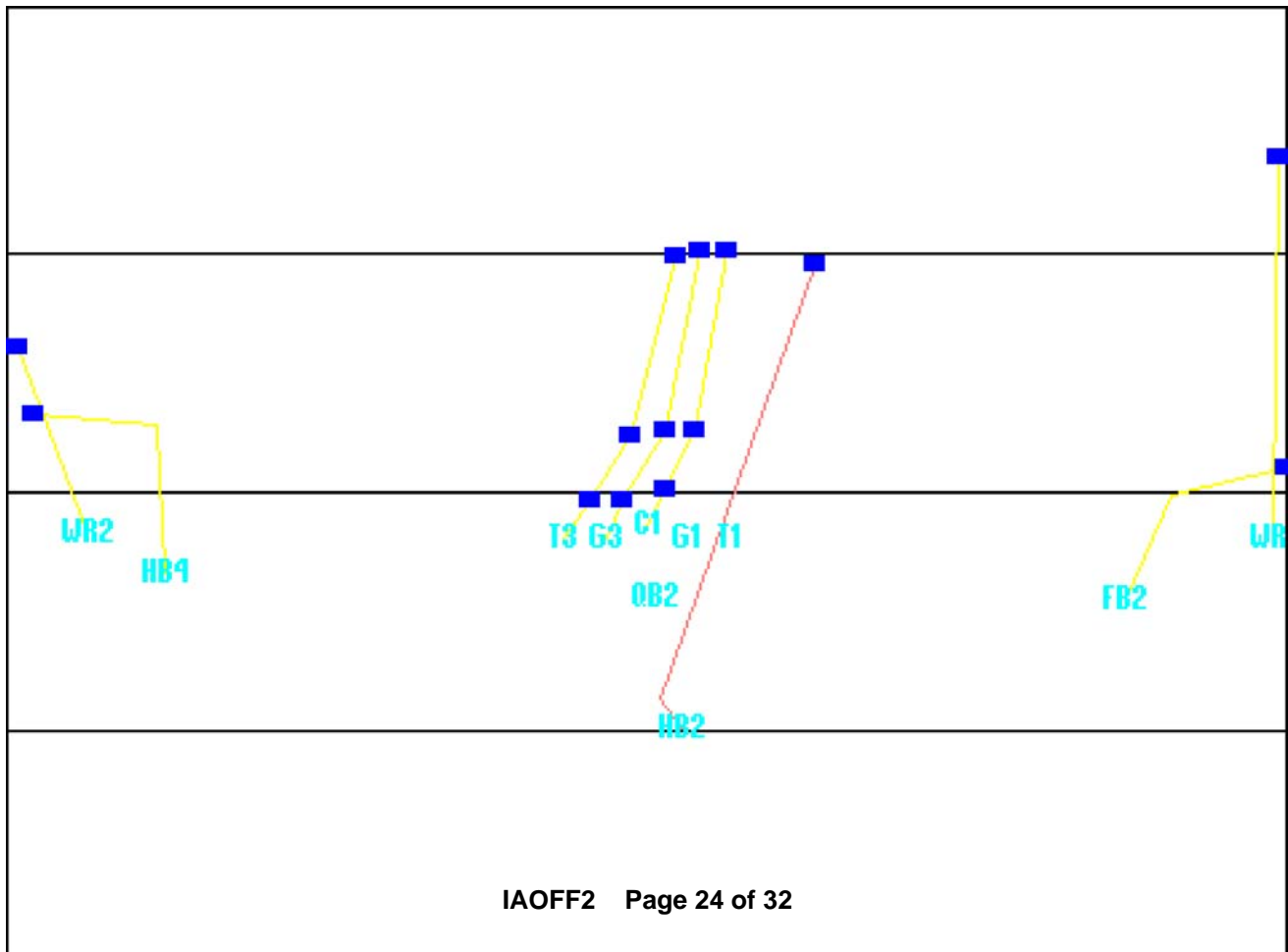


The diagram illustrates the layout of a 1000-point grid in a 2D coordinate system. The grid is divided into three main sections: a central cluster of points (T1, G1, C1, G3, T3, OB2, HB2) and two side clusters (HB1, WR1, WR2). The points are connected by lines, and the layout is defined by a set of horizontal and vertical lines.

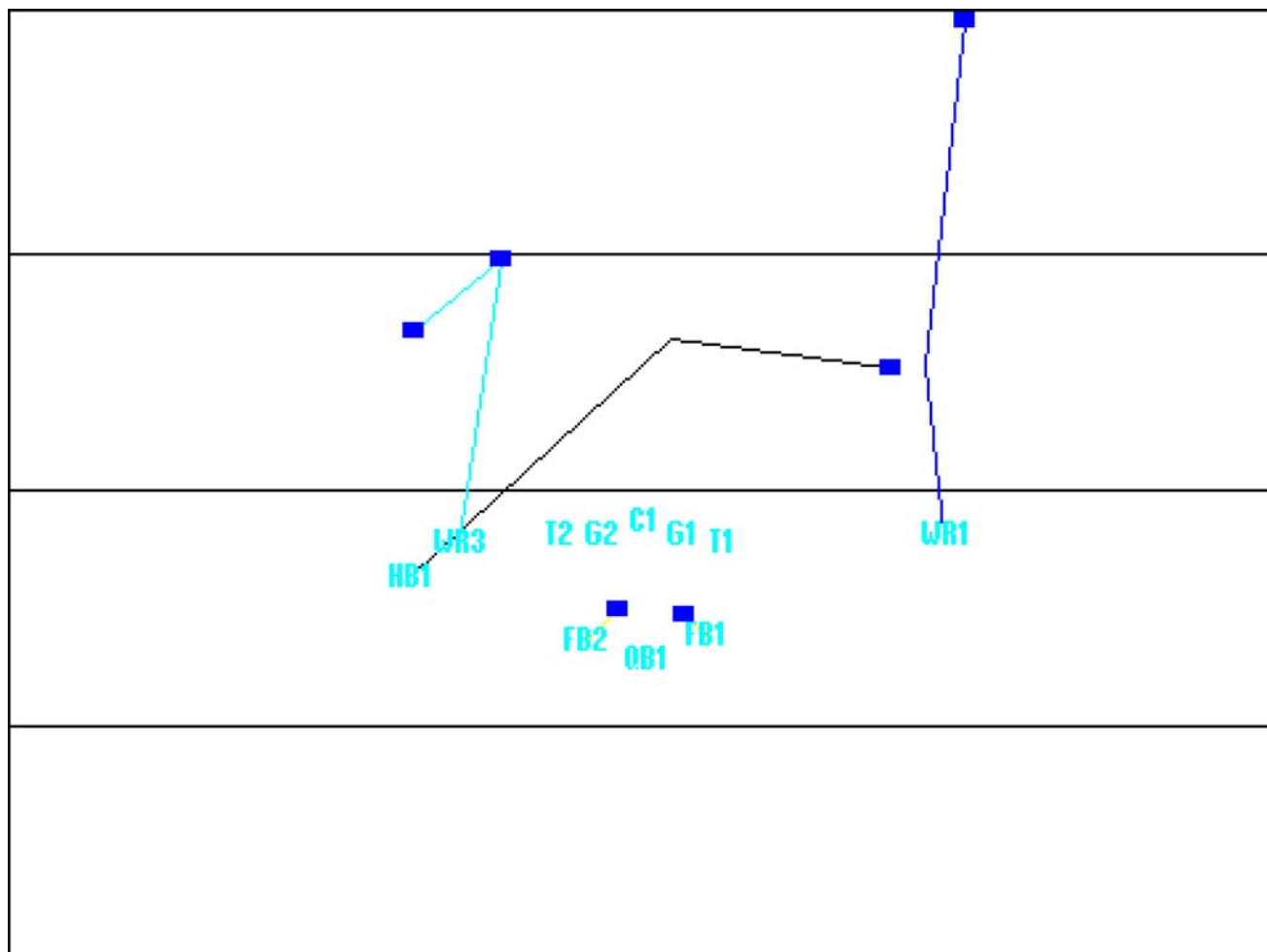
12-3 - PLRHwk1 - PASS LONG RIGHT



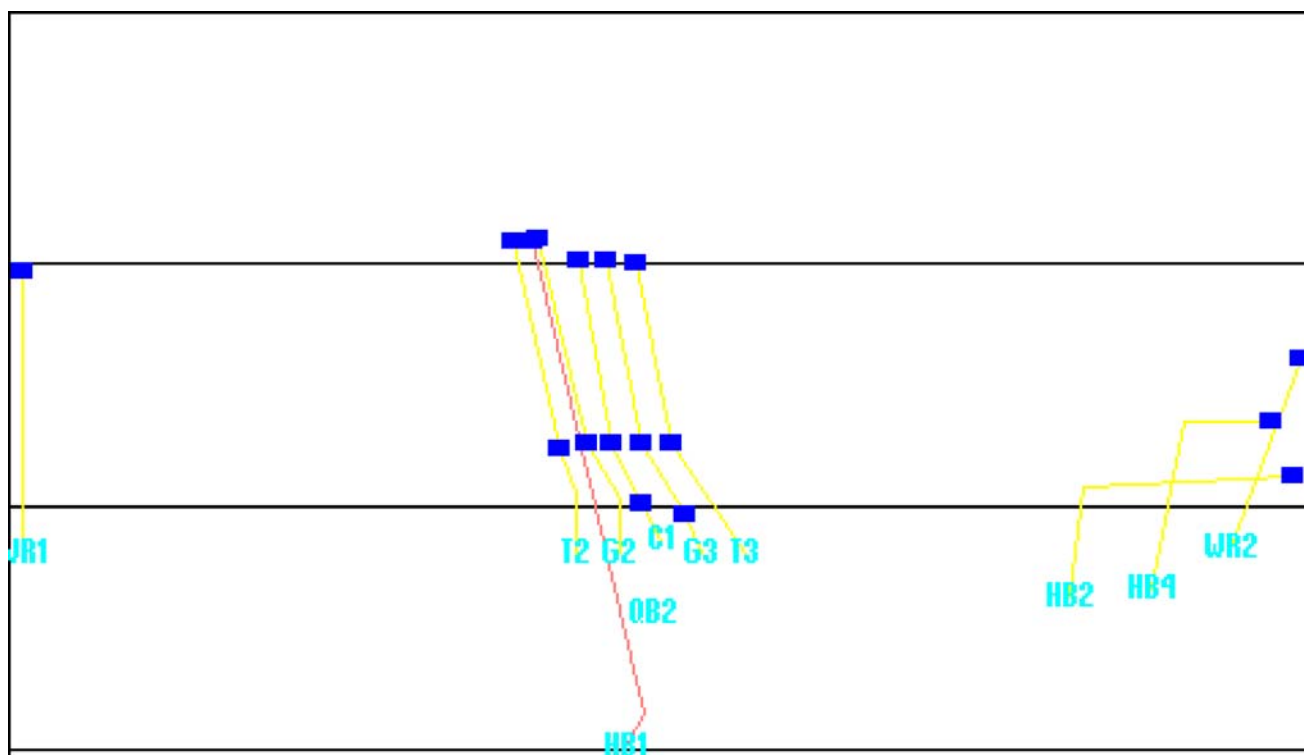
12-4 - PLRHwk2 - PASS LONG RIGHT



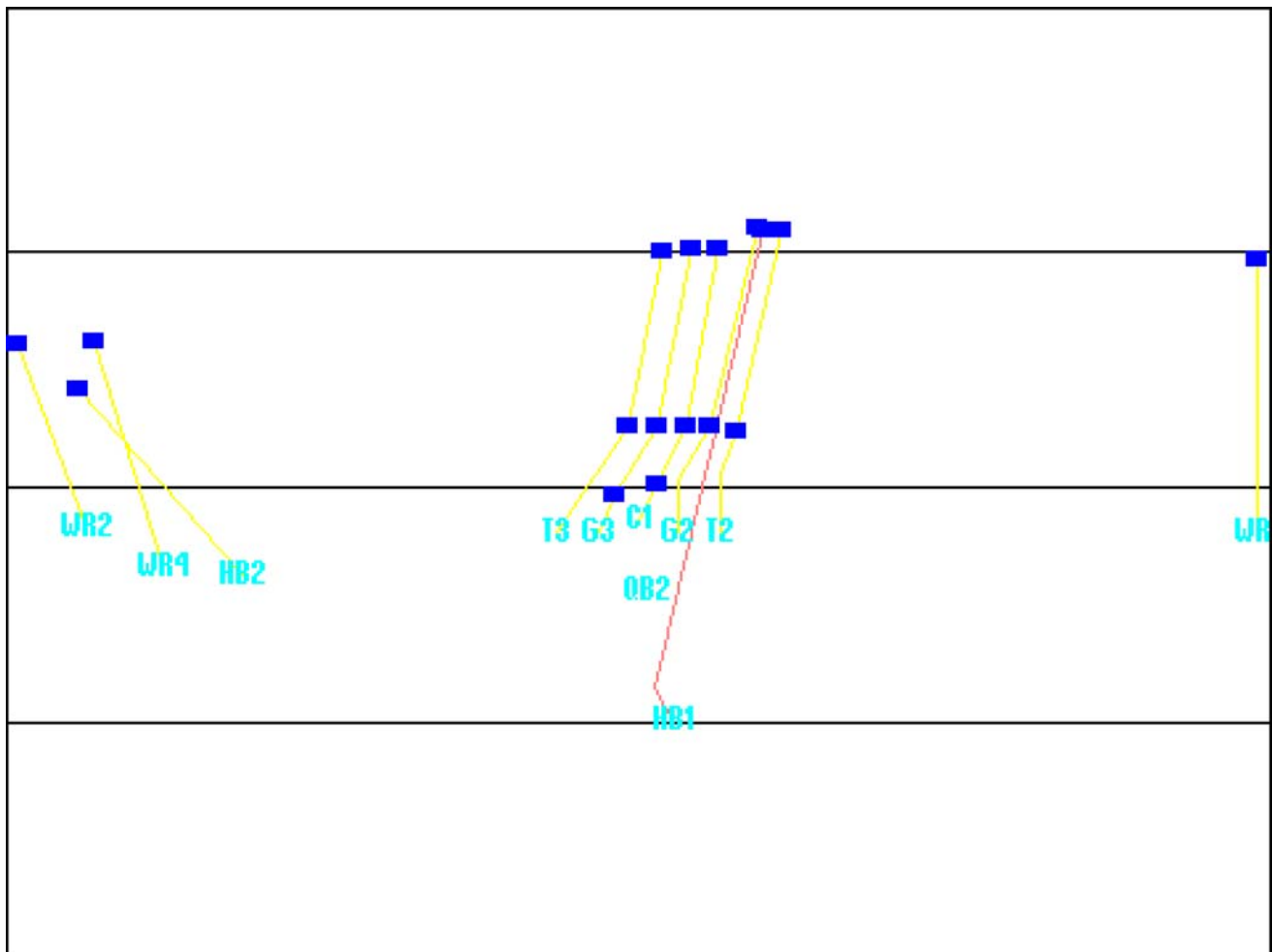
13-1 - PLMH1crs - PASS LONG MID.



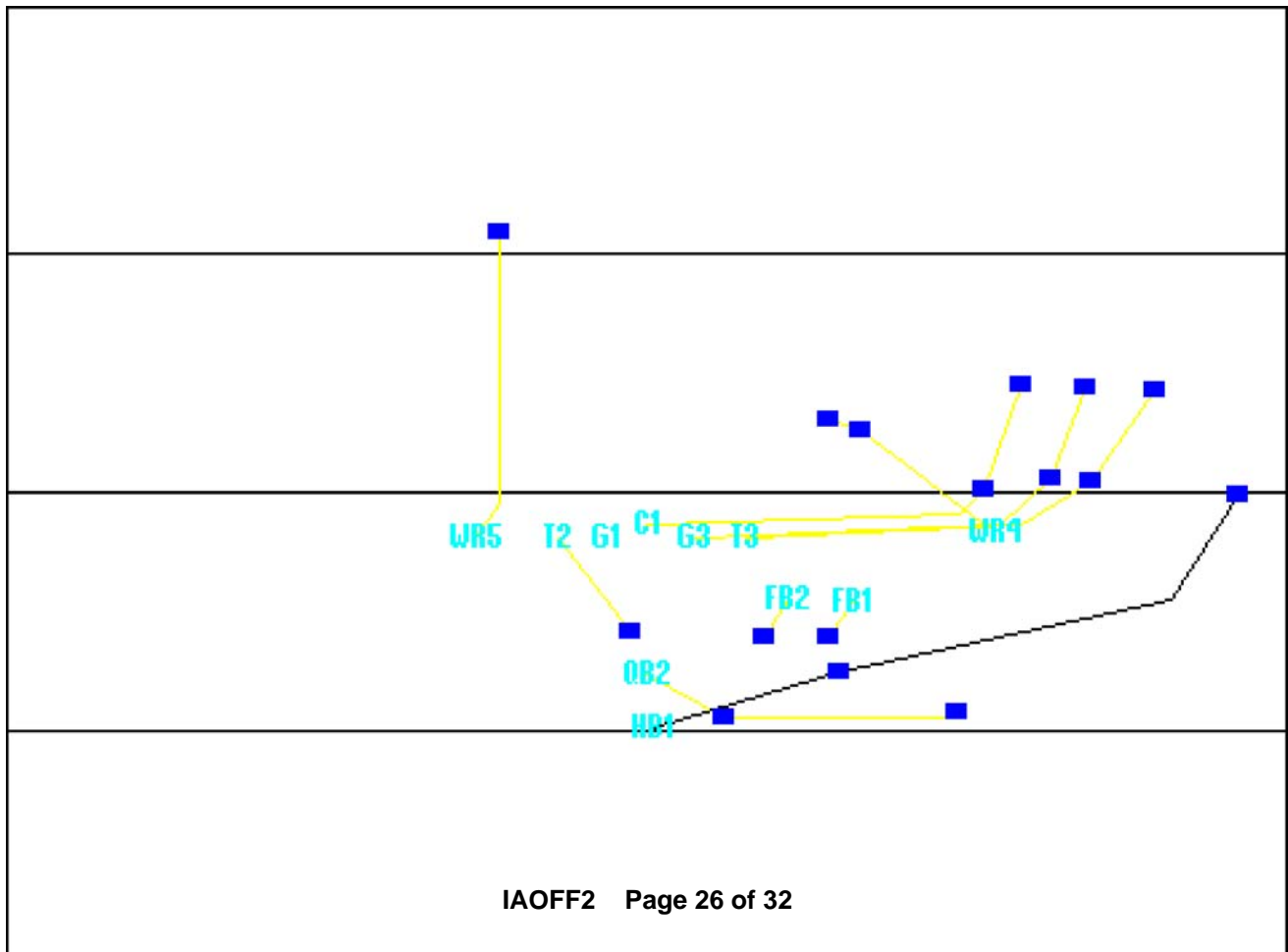
13-2 - PLMHB1JB - PASS LONG MID.



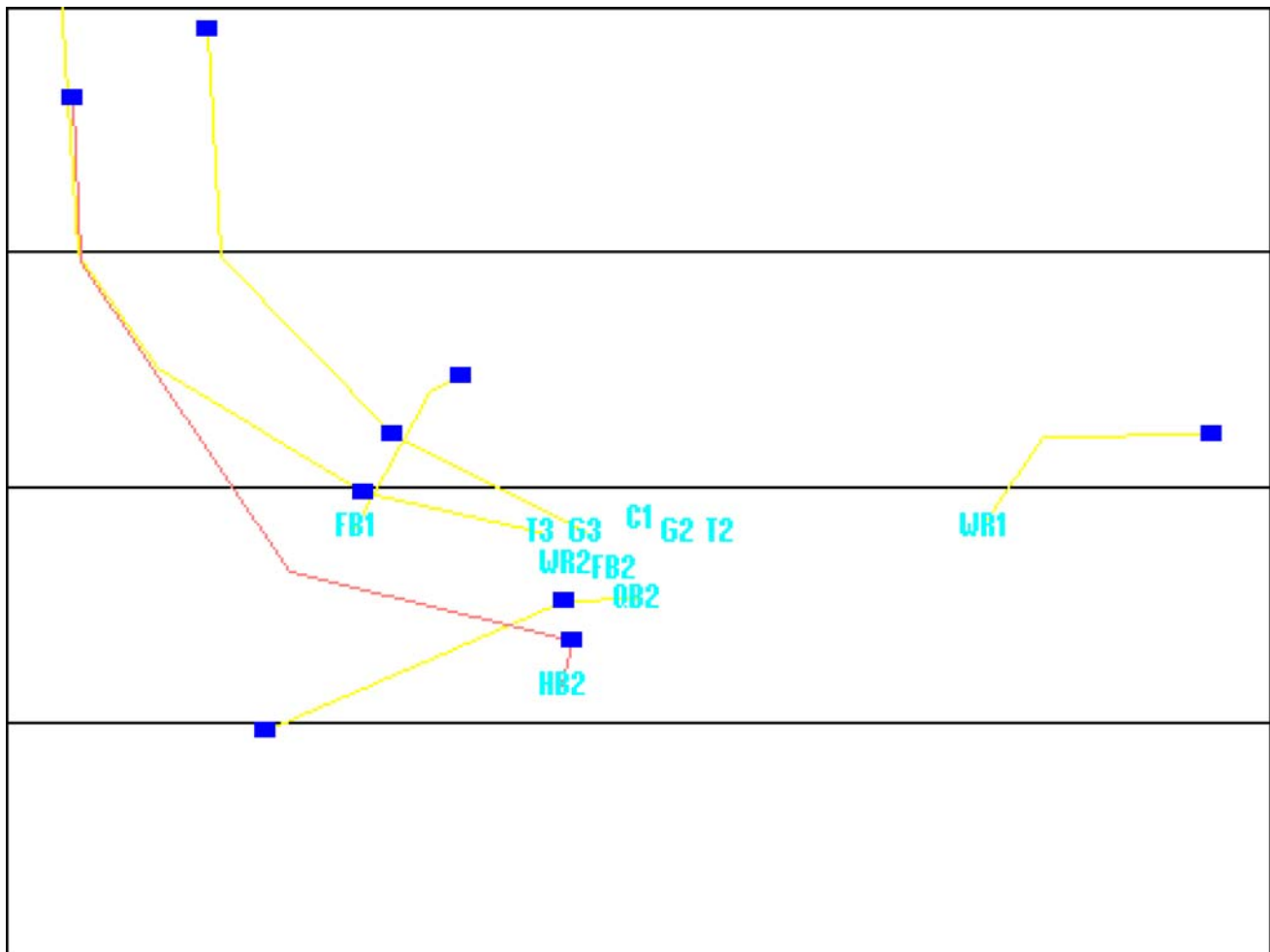
13-3 - PLMHB1-4 - PASS LONG MID.



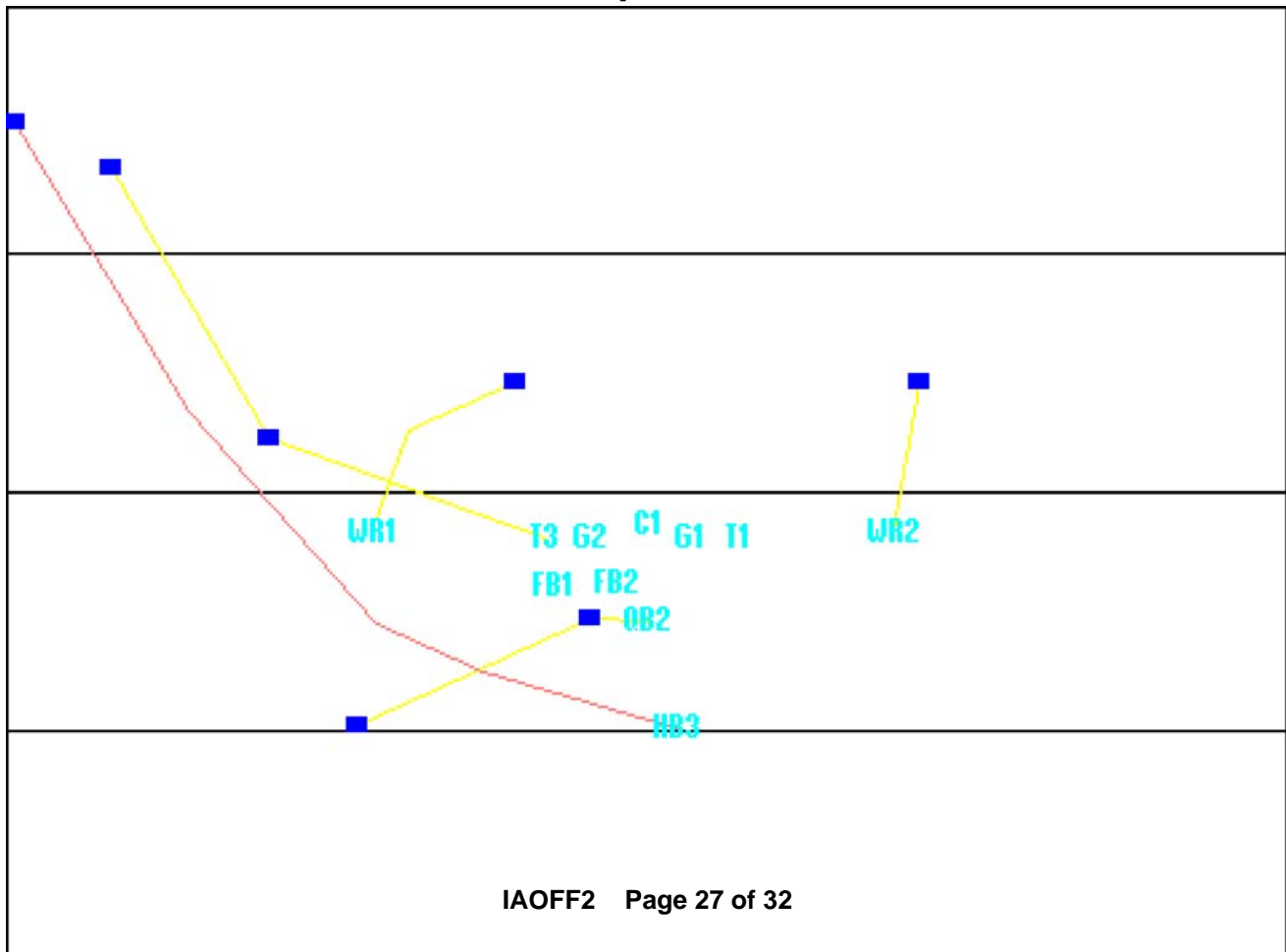
13-4 - PLMBULL1 - PASS LONG MID.



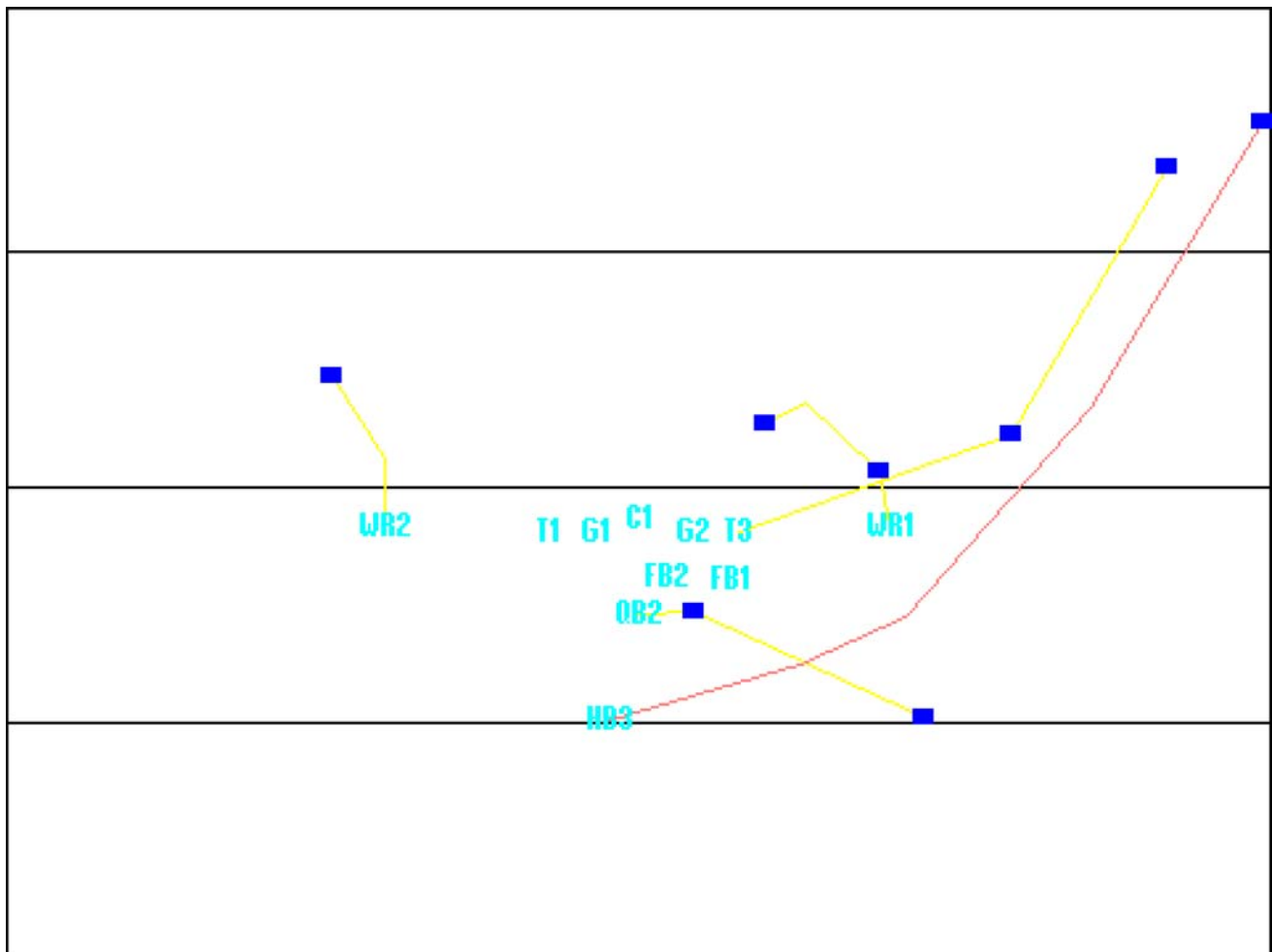
14-1 - PLLsw1 - PASS LONG LEFT



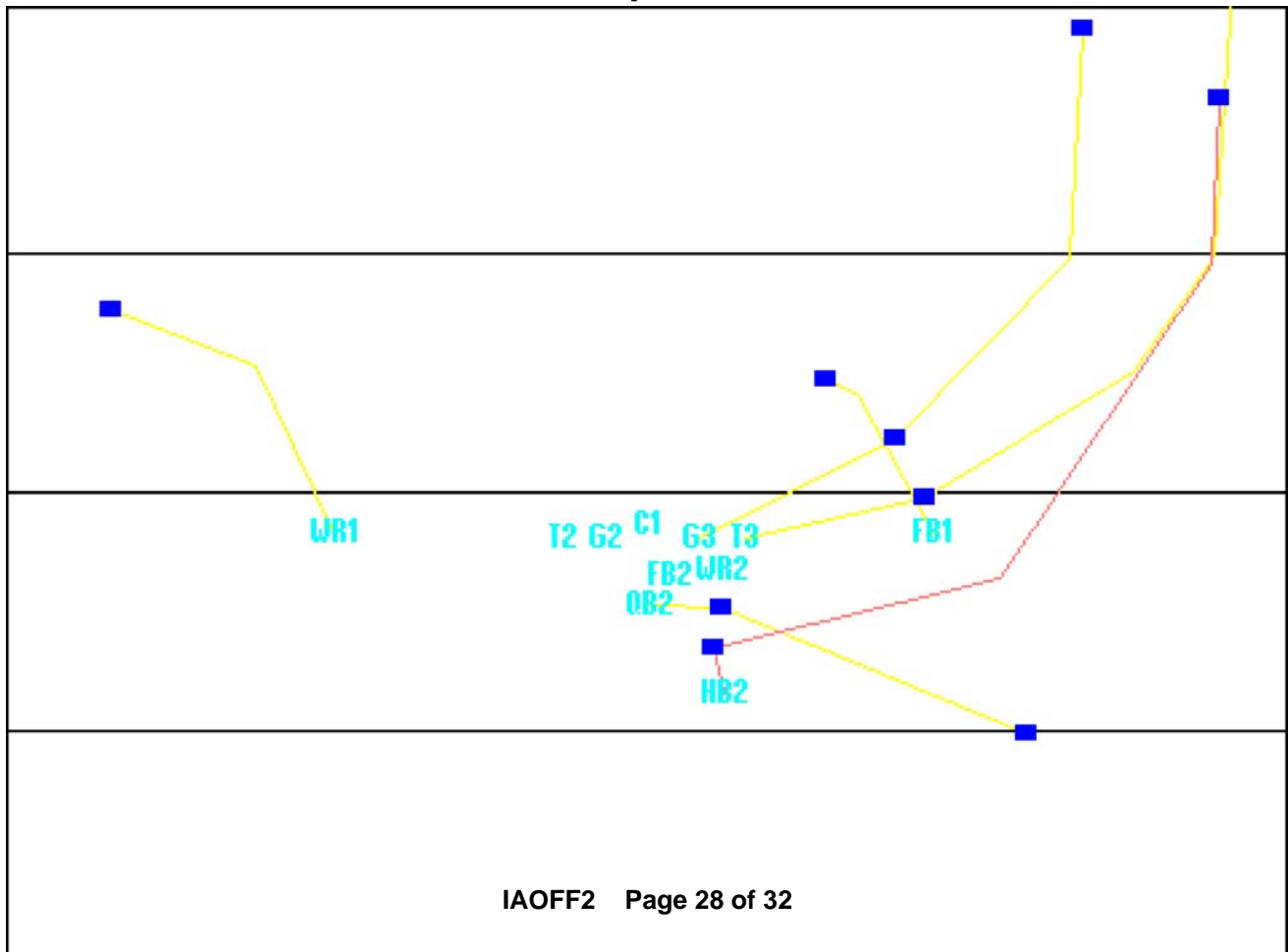
14-2 - PLLHamp5 - PASS LONG LEFT



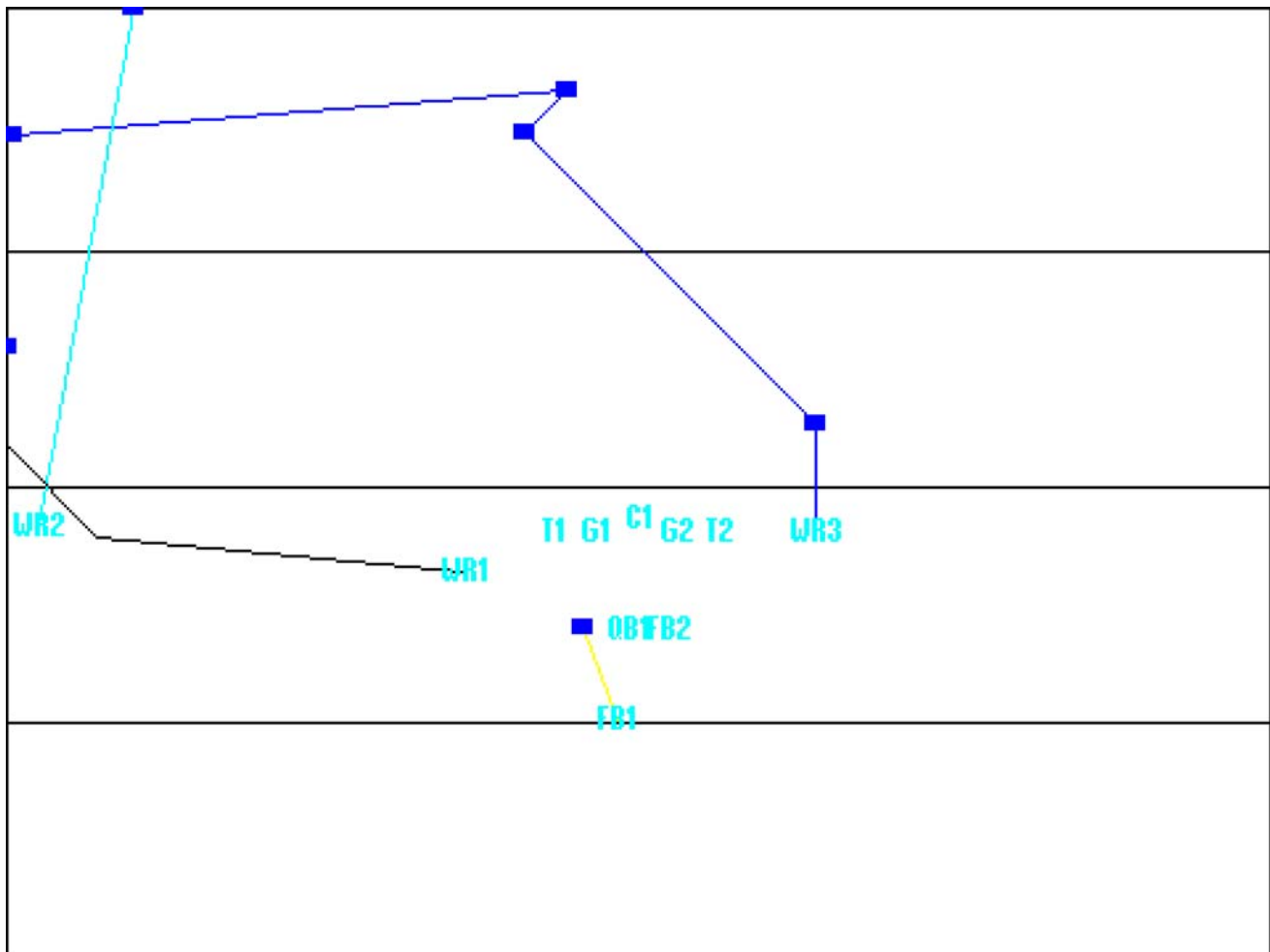
14-3 - PLLHamp2 - PASS LONG LEFT



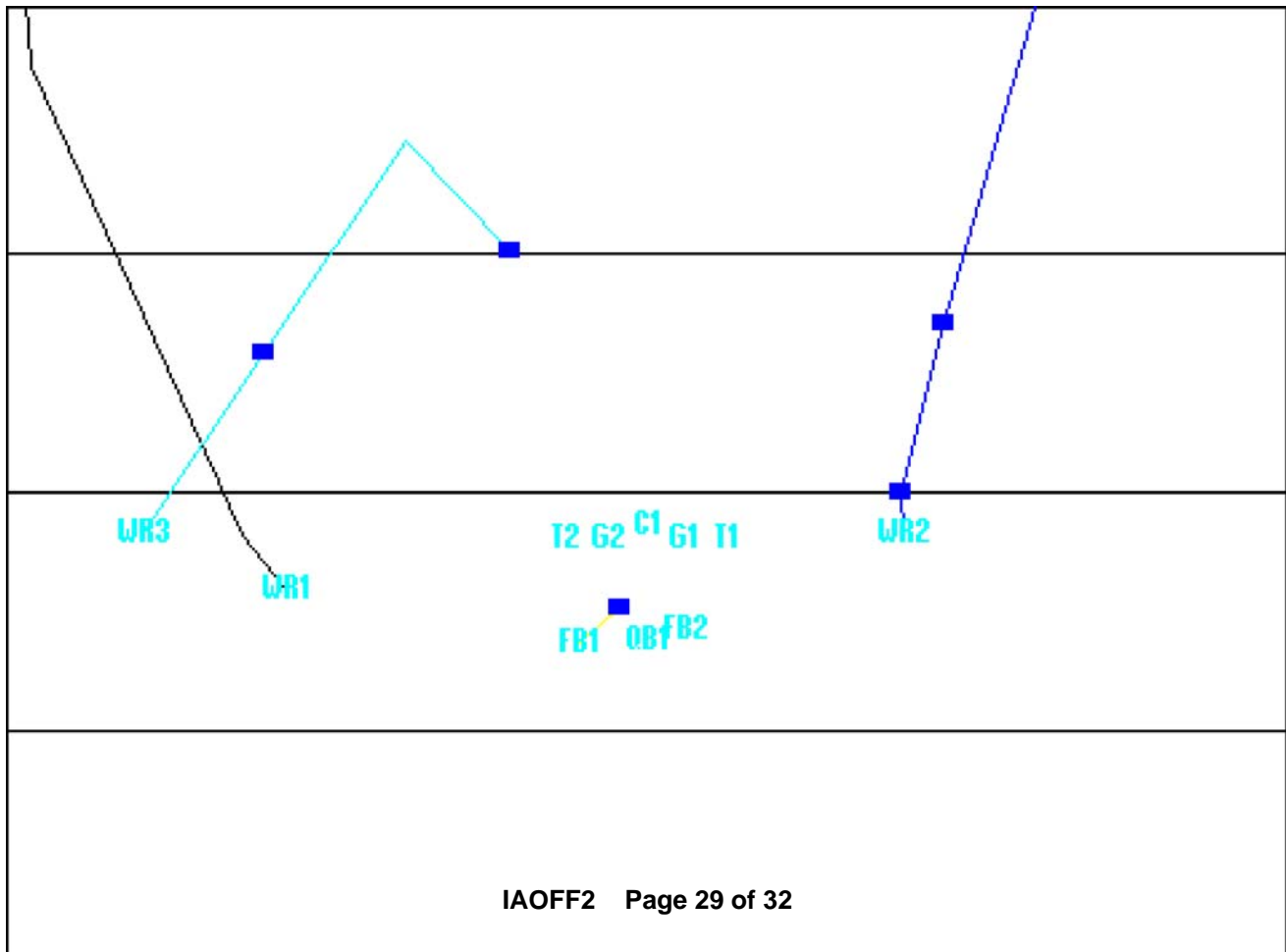
14-4 - PLLsweep - PASS LONG LEFT



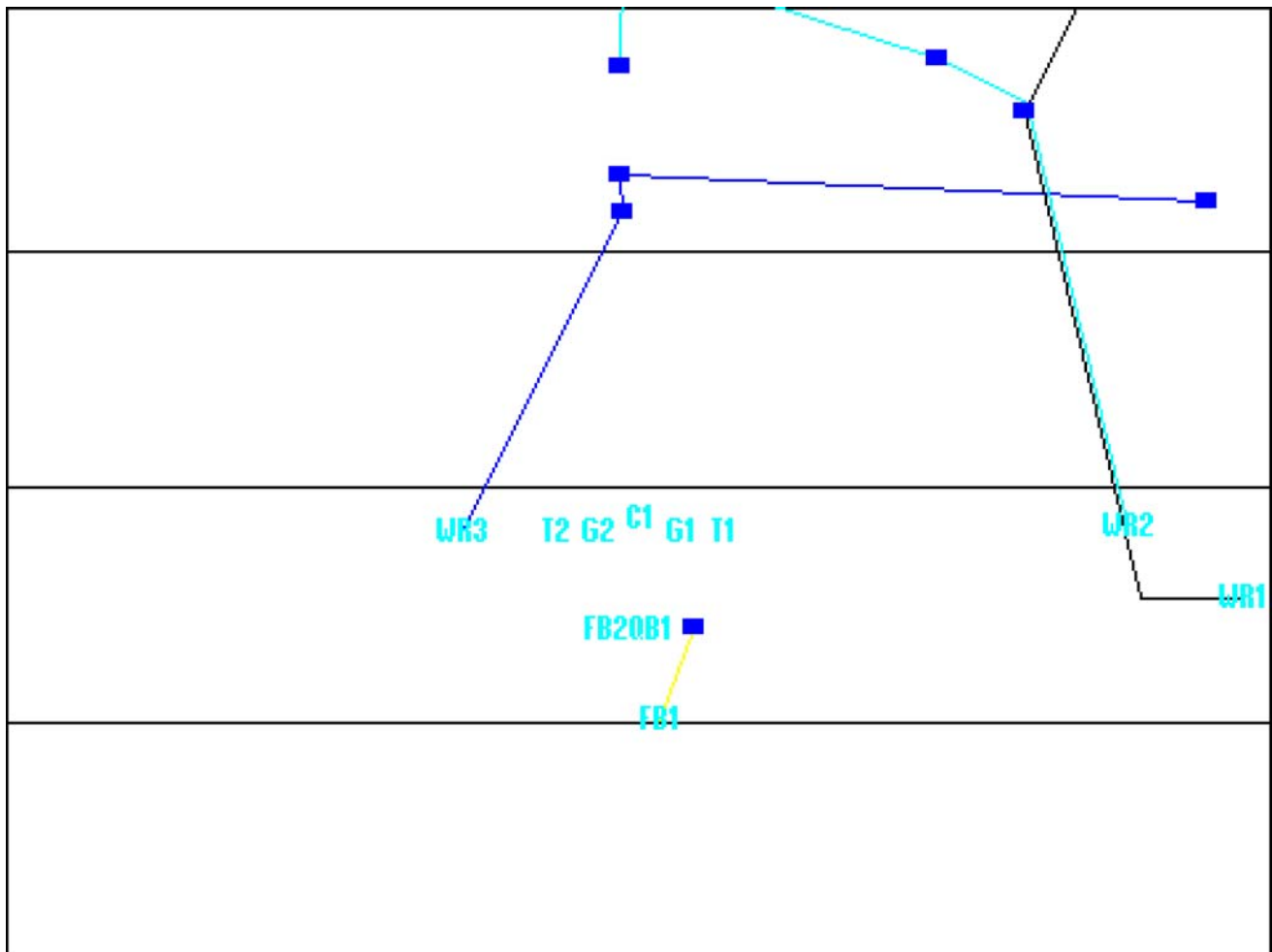
15-1 - RZPSD4 - RAZZ DAZZ PASS



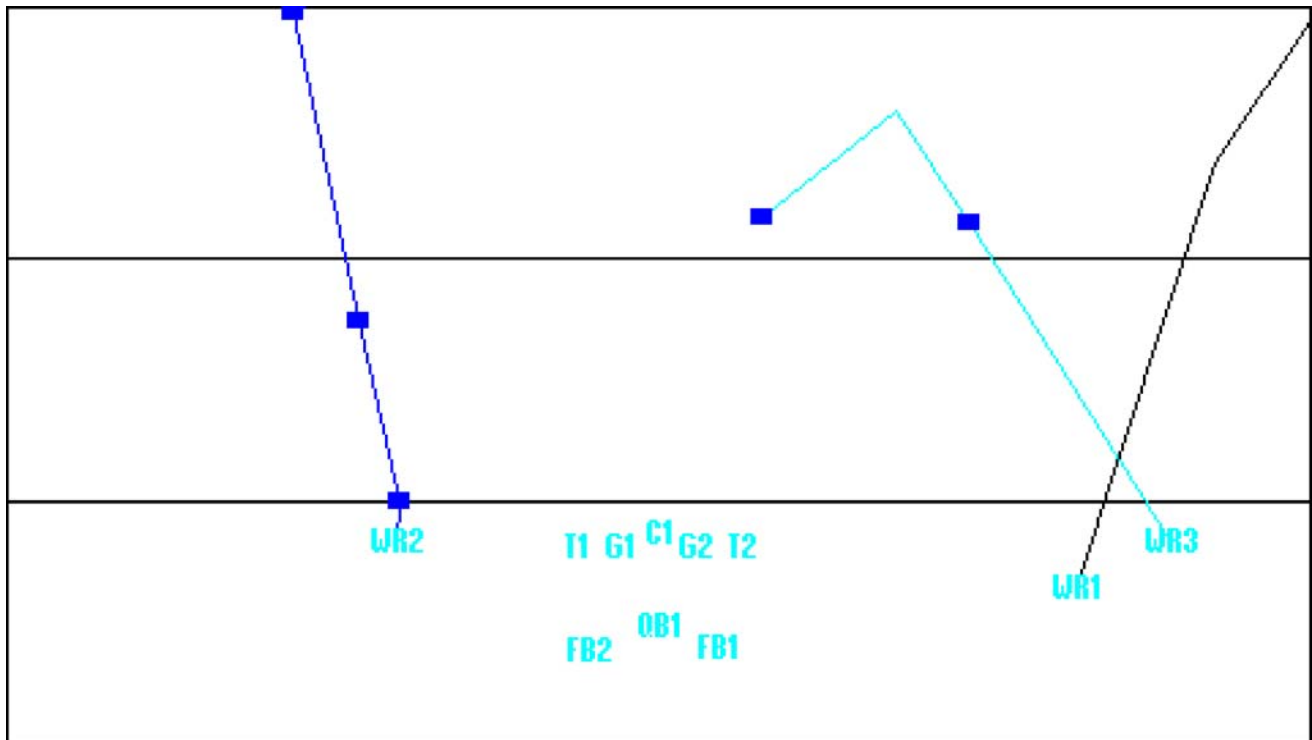
15-2 - RAZOLD1 - RAZZ DAZZ PASS



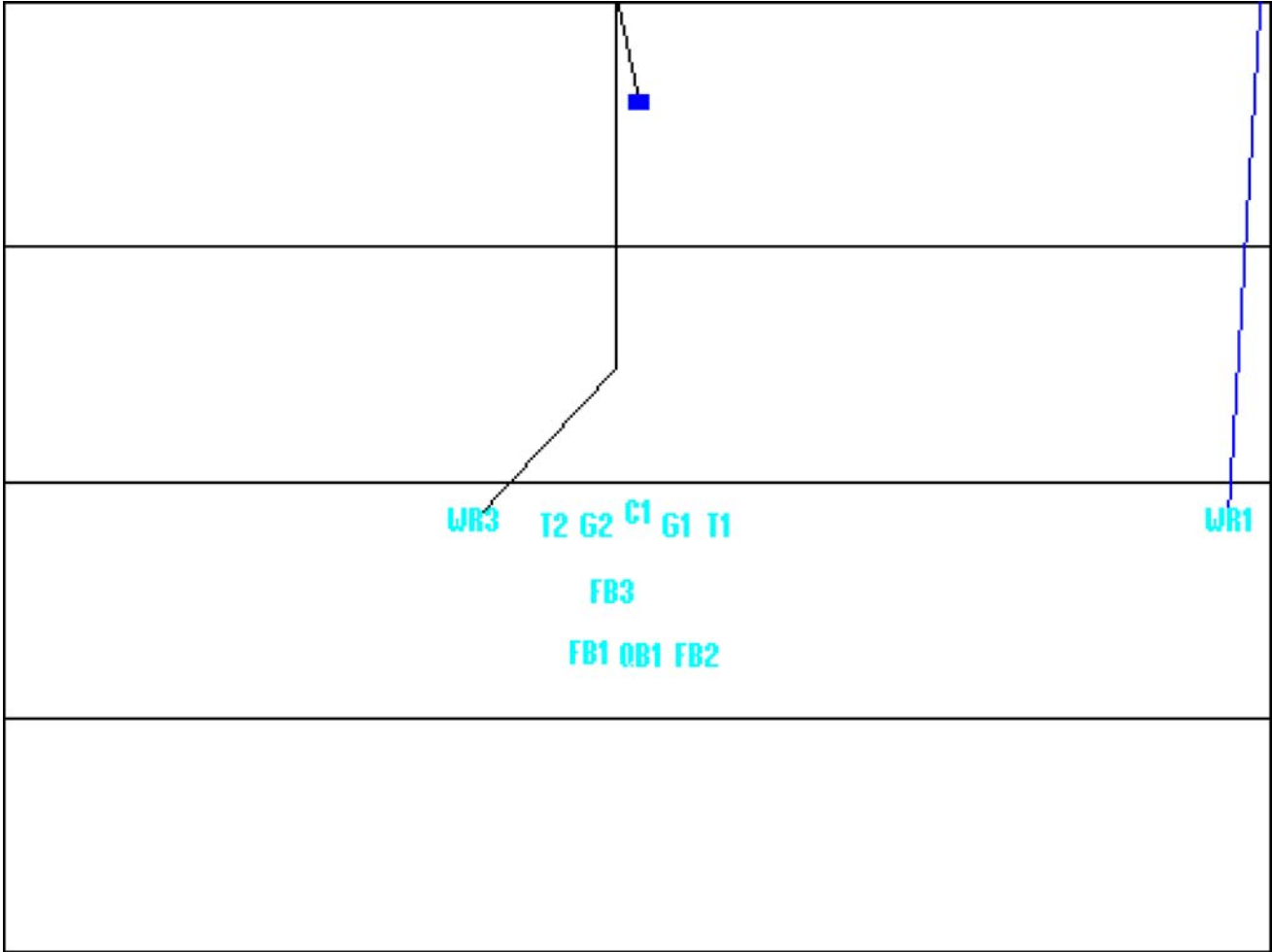
15-3 - RZ53009 - RAZZ DAZZ PASS



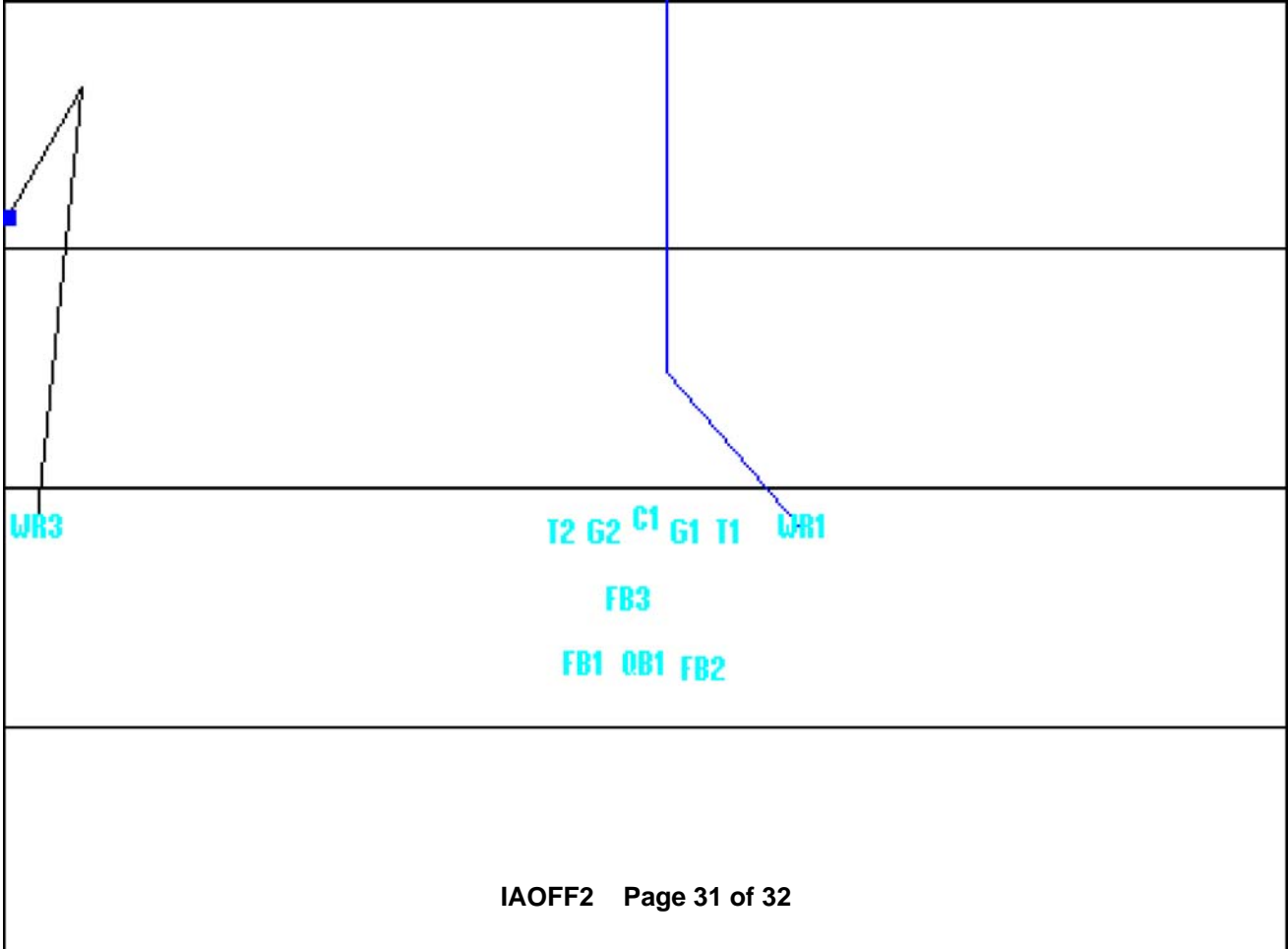
15-4 - RZPS1R - RAZZ DAZZ PASS



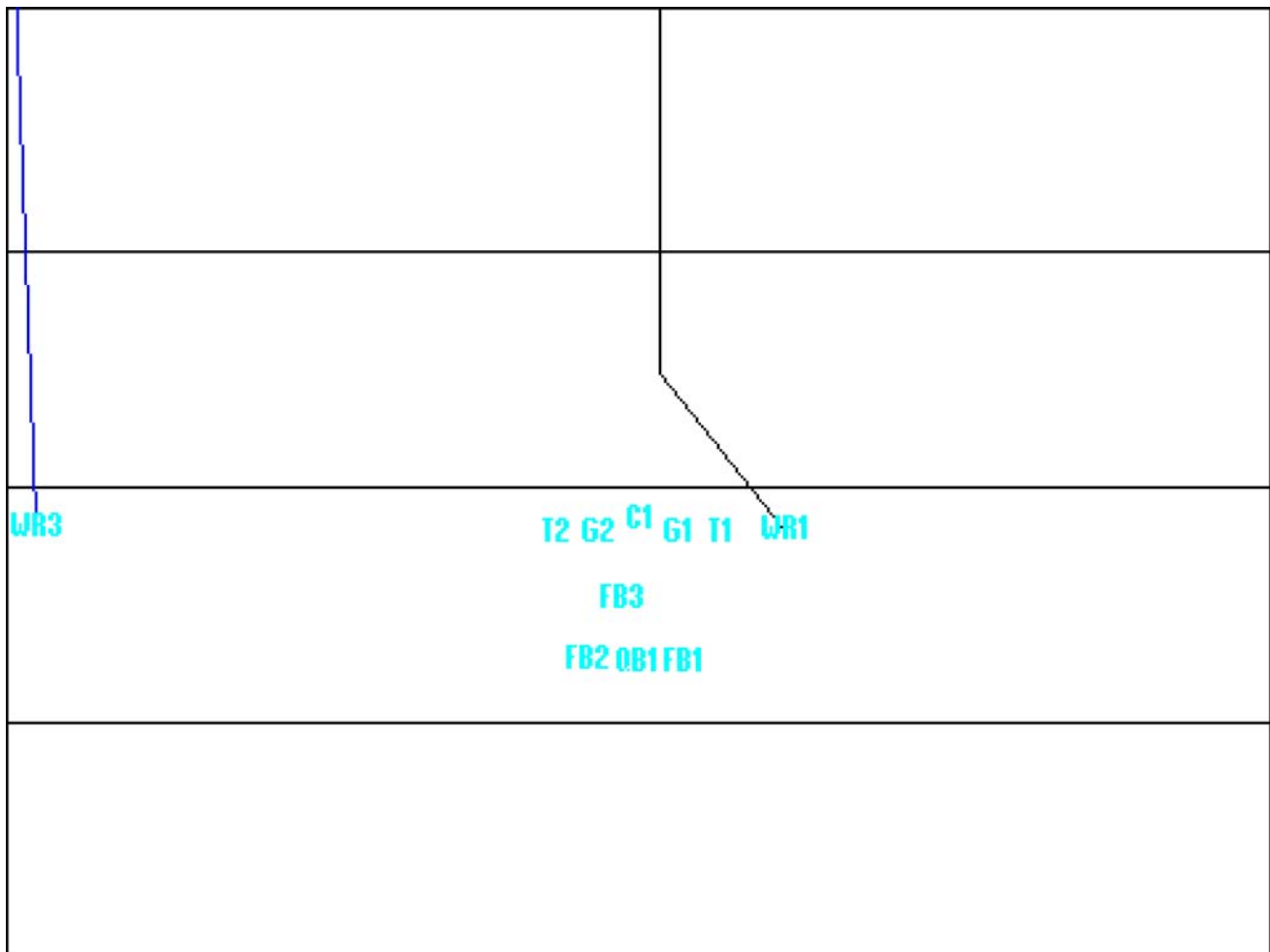
16-1 - RAZR1 - RAZZ DAZZ RUN



16-2 - RAZRA3 - RAZZ DAZZ RUN



16-3 - RAZRN1 - RAZZ DAZZ RUN



16-4 - RAZR4 - RAZZ DAZZ RUN

